PART - I

## TYPICAL QUESTIONS \& ANSWERS

OBJECTIVE TYPE QUESTIONS

## Each Question carries 2 marks.

## Choose the correct or best alternative in the following:

Q. 1 The discrete-time signal $x(n)=(-1)^{n}$ is periodic with fundamental period
(A) 6
(B) 4
(C) 2
(D) 0

Ans: C Period = 2

Q. 2 The frequency of a continuous time signal $\mathrm{x}(\mathrm{t})$ changes on transformation from $\mathrm{x}(\mathrm{t})$ to $\mathrm{x}(\alpha \mathrm{t}), \alpha>0$ by a factor
(A) $\alpha$.
(B) $\frac{1}{\alpha}$.
(C) $\alpha^{2}$.
(D) $\sqrt{\alpha}$.
Transform

Ans: $\mathbf{A x}(\mathrm{t}) \longrightarrow \mathrm{x}(\alpha \mathrm{t}), \alpha>0$
$\alpha>1 \Rightarrow$ compression in t , expansion in f by $\alpha$. $\alpha<1 \Rightarrow$ expansion in $t$, compression in $f$ by $\alpha$.

Q. 3 A useful property of the unit impulse $\delta(\mathrm{t})$ is that
(A) $\delta(\mathrm{at})=\mathrm{a} \delta(\mathrm{t})$.
(B) $\delta(a t)=\delta(t)$.
(C) $\delta(\mathrm{at})=\frac{1}{\mathrm{a}} \delta(\mathrm{t})$.
(D) $\delta(\mathrm{at})=[\delta(\mathrm{t})]^{\mathrm{a}}$.

Ans: C Time-scaling property of $\delta(\mathrm{t})$ :

$$
\delta(\mathrm{at})=\underline{1} \delta(\mathrm{t}), \mathrm{a}>0
$$

a
Q. 4 The continuous time version of the unit impulse $\delta(\mathrm{t})$ is defined by the pair of relations
(A) $\delta(\mathrm{t})= \begin{cases}1 & \mathrm{t}=0 \\ 0 & \mathrm{t} \neq 0 .\end{cases}$
(B) $\delta(\mathrm{t})=1, \mathrm{t}=0$ and $\int_{-\infty}^{\infty} \delta(\mathrm{t}) \mathrm{dt}=1$.
(C) $\delta(\mathrm{t})=0, \mathrm{t} \neq 0$ and $\int_{-\infty}^{\infty} \delta(\mathrm{t}) \mathrm{dt}=1$.
(D) $\delta(\mathrm{t})=\left\{\begin{array}{l}1, \mathrm{t} \geq 0 \\ 0, \\ \mathrm{t}<0\end{array}\right.$.

Ans: $\mathbf{C} \delta(\mathrm{t})=0, \mathrm{t} \neq 0 \rightarrow \delta(\mathrm{t}) \neq 0$ at origin

$$
\begin{aligned}
& \int_{-\infty}^{+\infty} \delta(\mathrm{t}) \mathrm{dt}=1 \rightarrow \text { Total area under the curve is unity. } \\
& {[\delta(\mathrm{t}) \text { is also called Dirac-delta function }]}
\end{aligned}
$$

Q. 5 Two sequences $x_{1}(n)$ and $x_{2}(n)$ are related by $x_{2}(n)=x_{1}(-n)$. In the $z-$ domain, their ROC's are
(A) the same.
(B) reciprocal of each other.
(C) negative of each other.
(D) complements of each other.

Q. 6 The Fourier transform of the exponential signal $e^{j \omega_{0} t}$ is
(A) a constant.
(B) a rectangular gate.
(C) an impulse.
(D) a series of impulses.

Ans: C Since the signal contains only a high frequency $\omega_{0}$ its FT must be an impulse at $\omega=\omega_{0}$
Q. 7 If the Laplace transform of $f(t)$ is $\frac{\omega}{\left(s^{2}+\omega^{2}\right)}$, then the value of $\operatorname{Lim}_{t \rightarrow \infty} f(t)$
(A) cannot be determined.
(B) is zero.
(C) is unity.
(D) is infinity.

L
Ans: Bf(t)


$$
\begin{aligned}
\operatorname{Lim}_{t \rightarrow \infty} f(t) & =\operatorname{Lim}_{s \longrightarrow 0} s F(s) \quad[\text { Final value theorem }] \\
& =\underset{s \longrightarrow 0}{\operatorname{Lim}}\left(\frac{s \omega}{s^{2}+\omega^{2}}\right)=0
\end{aligned}
$$

Q. 8 The unit impulse response of a linear time invariant system is the unit step function $u(t)$. For $t>0$, the response of the system to an excitation $e^{-a t} u(t), a>0$, will be
(A) $\mathrm{ae}^{-\mathrm{at}}$.
(B) $\frac{1-\mathrm{e}^{-\mathrm{at}}}{\mathrm{a}}$.
(C) $\mathrm{a}\left(1-\mathrm{e}^{-\mathrm{at}}\right)$.
(D) $1-\mathrm{e}^{-\mathrm{at}}$.

## Ans: B

$$
\mathrm{h}(\mathrm{t})=\mathrm{u}(\mathrm{t}) ; \quad \mathrm{x}(\mathrm{t})=\mathrm{e}^{-\mathrm{at}} \mathrm{u}(\mathrm{t}), \mathrm{a}>0
$$

$$
\begin{aligned}
\text { System response } \mathrm{y}(\mathrm{t}) & =L^{-1}\left[\frac{1}{s} \cdot \frac{1}{s+a}\right] \\
& =L^{-1} \frac{1}{a}\left[\frac{1}{s}-\frac{1}{s+a}\right] \\
& =\frac{1}{\mathrm{a}}\left(1-\mathrm{e}^{-\mathrm{at}}\right)
\end{aligned}
$$

Q. 9 The z-transform of the function $\sum_{\mathrm{k}=-\infty}^{0} \delta(\mathrm{n}-\mathrm{k})$ has the following region of convergence
(A) $|z|>1$
(B) $|z|=1$
(C) $|z|<1$
(D) $0<|z|<1$

Ans: $\quad \mathbf{C} \quad \mathrm{x}(\mathrm{n})=\sum_{\mathrm{k}=-\infty}^{0} \delta(\mathrm{n}-\mathrm{k})$

$$
\begin{aligned}
x(z) & =\sum_{k=-\infty}^{0} z^{-k}=\ldots .+z^{3}+z^{2}+z+1 \quad \text { (Sum of infinite geometric series) } \\
& =\frac{1}{1-z}, \quad|z|<1
\end{aligned}
$$

Q. 10 The auto-correlation function of a rectangular pulse of duration T is
(A) a rectangular pulse of duration T .
(B) a rectangular pulse of duration 2 T .
(C) a triangular pulse of duration T .
(D) a triangular pulse of duration 2 T .

Ans: D
$\mathrm{R}_{\mathrm{XX}}(\tau)=\frac{1}{\mathrm{~T}} \int_{-\mathrm{T} / 2}^{\mathrm{T} / 2} \mathrm{x}(\tau) \mathrm{x}(\mathrm{t}+\tau) \mathrm{d} \tau \Rightarrow$ triangular function of duration 2 T.
Q. 11 The Fourier transform (FT) of a function $x(t)$ is $X(f)$. The FT of $d x(t) / d t$ will be
(A) $\mathrm{dX}(\mathrm{f}) / \mathrm{df}$.
(B) $\mathrm{j} 2 \pi \mathrm{f} \mathrm{X}(\mathrm{f})$.
(C) $\mathrm{jf} \mathrm{X}(\mathrm{f})$.
(D) $\mathrm{X}(\mathrm{f}) /(\mathrm{jf})$.

Ans: $B(t)=\frac{1}{2 \pi} \int_{-\infty}^{\infty} X(f) e^{j \omega t} d \omega$

$$
\begin{aligned}
& \frac{d_{-} \mathrm{X}}{\mathrm{dt}}=\frac{1}{2 \pi} \int_{-\infty}^{\infty} \mathrm{j} \omega \mathrm{X}(\mathrm{f}) \mathrm{e}^{\mathrm{j} \omega \mathrm{t}} \mathrm{~d} \omega \\
\therefore & \frac{\mathrm{~d}_{-} \mathrm{x}}{\mathrm{dt}} \leftrightarrow \mathrm{j} 2 \pi \mathrm{f} X(\mathrm{f})
\end{aligned}
$$

Q. 12 The FT of a rectangular pulse existing between $\mathrm{t}=-\mathrm{T} / 2$ to $\mathrm{t}=\mathrm{T} / 2$ is a
(A) sinc squared function.
(B) sinc function.
(C) sine squared function.
(D) sine function.

Ans: $\mathbf{B} x(\mathrm{t})=\left[\begin{array}{ll}1, & -\frac{\mathrm{T}}{2} \leq \mathrm{t} \leq \frac{\mathrm{T}}{2} \\ 0, & \text { otherwise }\end{array}\right.$

$$
\begin{aligned}
X(j \omega) & =\int_{-\infty}^{+\infty} x(t) e^{-j \omega t} d t=\int_{-T / 2}^{+T / 2} e^{-j \omega t} d t=\left.\frac{e^{-j \omega t}}{j \omega}\right|_{-T / 2} ^{+T / 2} \\
& =\frac{-1}{j \omega}\left(e^{-j \omega T / 2}-e^{j \omega T / 2}\right)=\frac{2}{\omega}\left(\frac{e^{j \omega T / 2}-e^{-j \omega T / 2}}{2 j}\right) \\
& =\frac{2}{\omega} \sin \frac{\omega T}{2}=\frac{\sin (\omega T / 2)}{\omega T / 2} \cdot T
\end{aligned}
$$

Hence $X(\mathrm{j} \omega)$ is expressed in terms of a sinc function.
Q. 13 An analog signal has the spectrum shown in Fig. The minimum sampling rate needed to completely represent this signal is
(A) 3 KHz .
(B) 2 KHz .
(C) 1 KHz .
(D) 0.5 KHz .


Ans: C For a band pass signal, the minimum sampling rate is twice the bandwidth, which is 0.5 kHz here.
Q. 14 A given system is characterized by the differential equation:

$$
\frac{\mathrm{d}^{2} \mathrm{y}(\mathrm{t})}{\mathrm{dt}^{2}}-\frac{\mathrm{dy}(\mathrm{t})}{\mathrm{dt}}-2 \mathrm{y}(\mathrm{t})=\mathrm{x}(\mathrm{t}) .
$$

The system is :
(A) linear and unstable.
(B) linear and stable.
(C) nonlinear and unstable.
(D) nonlinear and stable.

Ans: A

$$
\frac{d^{2} y(t)}{d t^{2}}-\frac{d y(t)}{d t}-2 y(t)=x(t), x(t) \rightarrow \underset{\text { system }}{\mathrm{h}(\mathrm{t})} \longrightarrow y(t)
$$

The system is linear. Taking LT with zero initial conditions, we get $\mathrm{s}^{2} \mathrm{Y}(\mathrm{s})-\mathrm{sY}(\mathrm{s})-2 \mathrm{Y}(\mathrm{s})=\mathrm{X}(\mathrm{s})$

$$
\text { or, } \mathrm{H}(\mathrm{~s})=\frac{\mathrm{Y}(\mathrm{~s})}{\mathrm{X}(\mathrm{~s})}=\frac{1}{\mathrm{~s}^{2}-\mathrm{s}-2}=\frac{1}{(\mathrm{~s}-2)(\mathrm{s}+1)}
$$

Because of the pole at $\mathrm{s}=+2$, the system is unstable.
Q. 15 The system characterized by the equation $y(t)=a x(t)+b$ is
(A) linear for any value of $b$.
(B) linear if $\mathrm{b}>0$.
(C) linear if $\mathrm{b}<0$.
(D) non-linear.

Ans: D The system is non-linear because $x(t)=0$ does not lead to $y(t)=0$, which is a violation of the principle of homogeneity.
Q. 16 Inverse Fourier transform of $u(\omega)$ is
(A) $\frac{1}{2} \delta(\mathrm{t})+\frac{1}{\pi \mathrm{t}}$.
(B) $\frac{1}{2} \delta(\mathrm{t})$.
(C) $2 \delta(\mathrm{t})+\frac{1}{\pi \mathrm{t}}$.
(D) $\delta(\mathrm{t})+\operatorname{sgn}(\mathrm{t})$.

Ans: $\mathbf{A x}(\mathrm{t})=\mathrm{u}(\mathrm{t}) \stackrel{\mathrm{FT}}{\longleftrightarrow} \mathrm{X}(\mathrm{j} \omega)=\pi \frac{\delta(\omega)}{\mathrm{J} \omega}+1$
Duality property: $\mathrm{X}(\mathrm{jt}) \longleftrightarrow 2 \pi \mathrm{x}(-\omega)$
$\mathrm{u}(\omega) \longleftrightarrow \frac{1}{2} \delta(\mathrm{t})+\frac{1}{\pi \mathrm{t}}$
Q. 17 The impulse response of a system is $h(n)=a^{n} u(n)$. The condition for the system to be BIBO stable is
(A) a is real and positive.
(B) a is real and negative.
(C) $|\mathrm{a}|>1$.
(D) $|\mathrm{a}|<1$.

Ans: D Sum $S=\sum_{n=-\infty}^{+\infty}|h(n)|=\sum_{n=-\infty}^{+\infty}\left|a^{n} u(n)\right|$

$$
\begin{aligned}
& \leq \sum_{n=0}|a|^{n} \quad(\because u(n)=1 \text { for } n \geq 0) \\
& \leq \frac{1}{1-|a|} \text { if }|a|<1 .
\end{aligned}
$$

Q. 18 If $R_{1}$ is the region of convergence of $x(n)$ and $R_{2}$ is the region of convergence of $y(n)$, then the region of convergence of $x(n)$ convoluted $y(n)$ is
(A) $\mathrm{R}_{1}+\mathrm{R}_{2}$.
(B) $\mathrm{R}_{1}-\mathrm{R}_{2}$.
(C) $R_{1} \cap R_{2}$.
(D) $\mathrm{R}_{1} \cup \mathrm{R}_{2}$.

Ans:C $x(n) \longleftrightarrow X(z), \quad \operatorname{RoC} R_{1}$

$\mathrm{x}(\mathrm{n}) * \mathrm{y}(\mathrm{n}) \stackrel{\mathrm{z}}{\longleftrightarrow} \mathrm{X}(\mathrm{z}) . \mathrm{Y}(\mathrm{z})$, RoC at least $\mathrm{R}_{1} \cap \mathrm{R}_{2}$
Q. 19 The continuous time system described by $y(t)=x\left(t^{2}\right)$ is
(A) causal, linear and time varying.
(B) causal, non-linear and time varying.
(C) non causal, non-linear and time-invariant.
(D) non causal, linear and time-invariant.

Ans: D
$\mathrm{y}(\mathrm{t})=\mathrm{x}\left(\mathrm{t}^{2}\right)$
$y(t)$ depends on $x\left(t^{2}\right)$ i.e., future values of input if $t>1$.
$\therefore$ System is anticipative or non-causal

$$
\begin{aligned}
& \alpha \mathrm{x}_{1}(\mathrm{t}) \rightarrow \mathrm{y}_{1}(\mathrm{t})=\alpha \mathrm{x}_{1}\left(\mathrm{t}^{2}\right) \\
& \beta \mathrm{x}_{2}(\mathrm{t}) \rightarrow \mathrm{y}_{2}(\mathrm{t})=\beta \mathrm{x}_{2}\left(\mathrm{t}^{2}\right) \\
& \therefore \alpha \mathrm{x}_{1}(\mathrm{t})+\beta \mathrm{x}_{2}(\mathrm{t}) \rightarrow \mathrm{y}(\mathrm{t})=\alpha \mathrm{x}_{1}\left(\mathrm{t}^{2}\right)+\beta \mathrm{x}_{2}\left(\mathrm{t}^{2}\right)=\mathrm{y}_{1}(\mathrm{t})+\mathrm{y}_{2}(\mathrm{t})
\end{aligned}
$$

. System is Linear
System is time varying. Check with $\mathrm{x}(\mathrm{t})=\mathrm{u}(\mathrm{t})-\mathrm{u}(\mathrm{t}-\mathrm{z}) \rightarrow \mathrm{y}(\mathrm{t})$ and
$\mathrm{x}_{1}(\mathrm{t})=\mathrm{x}(\mathrm{t}-1) \rightarrow \mathrm{y}_{1}(\mathrm{t})$ and find that $\mathrm{y}_{1}(\mathrm{t}) \neq \mathrm{y}(\mathrm{t}-1)$.
Q. 20 If $G(f)$ represents the Fourier Transform of a signal $g(t)$ which is real and odd symmetric in time, then $G(f)$ is
(A) complex.
(B) imaginary.
(C) real.
(D) real and non-negative.

$\mathrm{g}(\mathrm{t})$ real, odd symmetric in time
$G^{*}(j \omega)=-G(j \omega) ; G(j \omega)$ purely imaginary.
Q. 21 For a random variable x having the PDF shown in the Fig., the mean and the variance are, respectively,
(A) $1 / 2$ and $2 / 3$.
(B) 1 and $4 / 3$.
(C) 1 and $2 / 3$.
(D) 2 and $4 / 3$.


Ans:B Mean $=\mu_{\mathrm{x}}(\mathrm{t})=\int \mathrm{x} \mathrm{f}_{\mathrm{x}(\mathrm{t})}(\mathrm{x}) \mathrm{dx}$

$$
\begin{aligned}
& =\int_{-1}^{3} \mathrm{x} \frac{1}{4} \mathrm{dx}=\left.\frac{1}{4} \frac{x^{2}}{2}\right|_{-1} ^{3}=\left[\frac{9}{2}-\frac{1}{2}\right] \frac{1}{4}=1 \\
& \text { Variance }=\int_{-\infty}^{+\infty}\left(\mathrm{x}-\mu_{\mathrm{x}}\right)^{2} \mathrm{f}_{\mathrm{x}}(\mathrm{x}) \mathrm{dx} \\
& \\
& =\int_{-1}^{3}(\mathrm{x}-1)^{2} \frac{1}{4} \mathrm{~d}(\mathrm{x}-1) \\
& \\
& =\left.\frac{1}{4} \frac{(\mathrm{x}-1)^{3}}{3}\right|_{-1} ^{3}=\frac{1}{12}[8+8]=\frac{4}{3}
\end{aligned}
$$

Q. 22 If white noise is input to an RC integrator the ACF at the output is proportional to
(A) $\exp \left(\frac{-|\tau|}{\mathrm{RC}}\right)$.
(B) $\exp \left(\frac{-\tau}{\mathrm{RC}}\right)$.
(C) $\exp (|\tau| R C)$.
(D) $\exp (-\tau R C)$.

## Ans: A

$$
\mathrm{R}_{\mathrm{N}}(\tau)=\frac{\mathrm{N}_{0}}{4 \mathrm{RC}}\left(\exp \frac{-|\tau|}{\mathrm{RC}}\right)
$$

Q. $23 x(n)=a^{|n|},|a|<1$ is
(A) an energy signal.
(B) a power signal.
(C) neither an energy nor a power signal.
(D) an energy as well as a power signal.

$$
\begin{gathered}
\text { Ans: A } \quad \begin{array}{c}
\text { Energy }=\sum_{n=-\infty}^{+\infty} x^{2}(n)=\sum_{n=-\infty}^{\infty} a^{2|n|} \mid \\
=\sum_{n=-\infty}^{\infty}\left(a^{2}\right)^{|n|}=1+2 \sum_{n=1}^{\infty} a^{2} \\
=\text { finite since }|a|<1
\end{array}
\end{gathered}
$$

$\therefore$ This is an energy signal.
Q. 24 The spectrum of $x(n)$ extends from $-\omega_{0}$ to $+\omega_{0}$, while that of $h(n)$ extends

$$
\text { from }-2 \omega_{\mathrm{o}} \text { to }+2 \omega_{\mathrm{o}} . \text { The spectrum of } \mathrm{y}(\mathrm{n})=\sum_{\mathrm{k}=-\infty}^{\infty} \mathrm{h}(\mathrm{k}) \mathrm{x}(\mathrm{n}-\mathrm{k}) \text { extends }
$$

from
(A) $-4 \omega_{0}$ to $+4 \omega_{0}$.
(B) $-3 \omega_{\mathrm{o}}$ to $+3 \omega_{\mathrm{o}}$.
(C) $-2 \omega_{\mathrm{o}}$ to $+2 \omega_{\mathrm{o}}$.
(D) $-\omega_{\mathrm{o}}$ to $+\omega_{\mathrm{o}}$

Ans: D Spectrum depends on $H\left(\mathrm{e}^{\mathrm{j} \omega}\right) \longrightarrow \mathrm{X}\left(\mathrm{e}^{\mathrm{j} \omega}\right)$ Smaller of the two ranges.
Q. 25 The signals $x_{1}(t)$ and $x_{2}(t)$ are both bandlimited to $\left(-\omega_{1},+\omega_{1}\right)$ and
$\left(-\omega_{2},+\omega_{2}\right)$ respectively. The Nyquist sampling rate for the signal $x_{1}(t) x_{2}(t)$ will be
(A) $2 \omega_{1}$ if $\omega_{1}>\omega_{2}$.
(B) $2 \omega_{2}$ if $\omega_{1}<\omega_{2}$.
(C) $2\left(\omega_{1}+\omega_{2}\right)$.
(D) $\left(\omega_{1}+\omega_{2}\right) / 2$.

Ans: C Nyquist sampling rate $=2($ Bandwidth $)=2\left(\omega_{1}-\left(-\omega_{2}\right)\right)=2\left(\omega_{1}+\omega_{2}\right)$
Q. 26 If a periodic function $f(t)$ of period $T$ satisfies $f(t)=-f(t+T / 2)$, then in its Fourier series expansion,
(A)the constant term will be zero.
(B)there will be no cosine terms.
(C)there will be no sine terms.
(D)there will be no even harmonics.

## Ans:

$$
\frac{1}{T} \int_{0}^{T} f(t) d t=\frac{1}{T}\left(\int_{0}^{T / 2} f(t) d t+\int_{T / 2}^{T} f(t) d t\right)=\frac{1}{T}\left(\int_{0}^{T / 2} f(t) d t+\int_{0}^{T / 2} f(\tau+T / 2) d \tau\right)=0
$$

Q. 27 A band pass signal extends from 1 KHz to 2 KHz . The minimum sampling frequency needed to retain all information in the sampled signal is
(A) 1 KHz .
(B) 2 KHz .
(C) 3 KHz .
(D) 4 KHz .

Ans: B
Minimum sampling frequency $=2($ Bandwidth $)=2(1)=2 \mathrm{kHz}$
Q. 28 The region of convergence of the z-transform of the signal

$$
2^{n} u(n)-3^{n} u(-n-1)
$$

(A) is $|z|>1$.
(B) is $|z|<1$.
(C) is $2<|z|<3$.
(D) does not exist.

Ans:

$$
\begin{aligned}
& 2^{\mathrm{n}} \mathrm{u}(\mathrm{n}) \longleftrightarrow \frac{1}{1-2 \mathrm{z}^{-1}},|\mathrm{z}|>2 \\
& 3^{\mathrm{n}} \mathrm{u}(-\mathrm{n}-1) \longleftrightarrow \frac{1}{1-3 \mathrm{z}^{-1}},|\mathrm{z}|<3 \\
& \therefore \text { ROC is } 2<|\mathrm{z}|<3 .
\end{aligned}
$$

Q. 29 The number of possible regions of convergence of the function $\frac{\left(e^{-2}-2\right) z}{\left(z-e^{-2}\right)(z-2)}$ is
(A) 1 .
(B) 2 .
(C) 3 .
(D) 4 .

Ans: C
Possible ROC's are $|\mathrm{z}|>\mathrm{e}^{-2},|\mathrm{z}|<2$ and $\mathrm{e}^{-2}<|\mathrm{z}|<2$
Q. 30 The Laplace transform of $u(t)$ is $A(s)$ and the Fourier transform of $u(t)$ is $B(j \omega)$. Then
(A) $B(j \omega)=\left.A(s)\right|_{s=j \omega}$.
(B) $A(\mathrm{~s})=\frac{1}{\mathrm{~s}}$ but $\mathrm{B}(\mathrm{j} \omega) \neq \frac{1}{\mathrm{j} \omega}$.
(C) $\mathrm{A}(\mathrm{s}) \neq \frac{1}{\mathrm{~s}}$ but $\mathrm{B}(\mathrm{j} \omega)=\frac{1}{\mathrm{j} \omega}$.
(D) $A(\mathrm{~s}) \neq \frac{1}{\mathrm{~s}}$ but $\mathrm{B}(\mathrm{j} \omega) \neq \frac{1}{\mathrm{j} \omega}$.

Ans: $B \quad u(t) \stackrel{L}{\rightleftarrows} A(s)=\underline{1}$

$$
\mathrm{u}(\mathrm{t}) \stackrel{\text { F.T }}{\Longleftrightarrow} \mathrm{B}(\mathrm{j} \omega)=\frac{1}{\mathrm{j} \omega}+\pi \delta(\omega)
$$

$$
A(s)=\frac{1}{s} \text { but } B(j \omega) \neq \frac{1}{j \omega}
$$

PART - II

## NUMERICALS \& DERIVATIONS

Q.1. Determine whether the system having input $x$ ( n ) and output $\mathrm{y}(\mathrm{n})$ and described by relationship : $\quad y(n)=\sum_{k=-\infty}^{n} x(k+2)$
is (i) memoryless, (ii) stable, (iii)causal (iv) linear and (v) time invariant.
Ans:

$$
y(n)=\sum_{k=-\infty} x(k+2)
$$

(i) Not memoryless - as $y(n)$ depends on past values of input from $x(-\infty)$ to $x(n-1)$ (assuming) $\mathrm{n}>0$ )
(ii) Unstable- since if $|x(n)| \leq M$, then $|y(n)|$ goes to $\infty$ for any $n$.
(iii) Non-causal - as $\mathrm{y}(\mathrm{n})$ depends on $\mathrm{x}(\mathrm{n}+1)$ as well as $\mathrm{x}(\mathrm{n}+2)$.
(iv) Linear - $\because$ the principle of superposition applies (due to $\sum$ operation)
(v) Time - invariant $-\cdots$ a time-shift in input results in corresponding time-shift in output.
Q.2. Determine whether the signal $x(t)$ described by $x(t)=\exp [-a t] u(t), a>0$ is a power signal or energy signal or neither.

Ans:

$$
x(t)=e^{-a t} u(t), a>0
$$

$\mathrm{x}(\mathrm{t})$ is a non-periodic signal.

$$
\text { Energy } \mathrm{E}=\int_{-\infty}^{+\infty} \mathrm{x}^{2}(\mathrm{t}) \mathrm{dt}=\int_{0}^{\infty} \mathrm{e}^{-2 \mathrm{at}} \mathrm{dt}=\left.\frac{\mathrm{e}^{-2 a t}}{-2 \mathrm{a}}\right|_{0} ^{\infty}=\frac{1}{2 \mathrm{a}} \quad \text { (finite, positive) }
$$

The energy is finite and deterministic.
$\therefore \mathrm{x}(\mathrm{t})$ is an energy signal.
Q.3. Determine the even and odd parts of the signal $x(t)$ given by

$$
\begin{align*}
& x(t)= \begin{cases}A e^{-\alpha t} & t>0 \\
0 & t<0\end{cases} \\
& x(t)=\left\{\begin{array}{cc}
A e^{-\alpha t} & \underline{t}>0 \\
0 & t<0
\end{array}\right. \tag{5}
\end{align*}
$$

Ans:
Assumption : $\alpha>0, \mathrm{~A}>0,-\infty<\mathrm{t}<\infty$
Even part $\quad x_{e}(t)=\frac{x(t)+x(-t)}{2}$
Odd part $\quad \mathrm{x}_{\mathrm{o}}(\mathrm{t})=\frac{\mathrm{x}(\mathrm{t})-\mathrm{x}(-\mathrm{t})}{2}$

Q.4. Use one sided Laplace transform to determine the output $y(t)$ of a system described by

$$
\begin{equation*}
\frac{\mathrm{d}^{2} \mathrm{y}}{\mathrm{dt}^{2}}+3 \frac{\mathrm{dy}}{\mathrm{dt}}+2 \mathrm{y}(\mathrm{t})=0 \text { where } \mathrm{y}(0-)=3 \text { and }\left.\frac{\mathrm{dy}}{\mathrm{dt}}\right|_{\mathrm{t}=0-}=1 \tag{7}
\end{equation*}
$$

Ans:

$$
\begin{aligned}
& \frac{d^{2} y}{d t^{2}}+3 \frac{d y}{d t}+2 y(t)=0, \quad y(0-)=3, \frac{d y}{d t} t=0^{-}=1 \\
& \left(s^{2} Y(s)-s y(0)-\left.\frac{d y}{d t}\right|_{t=0}\right)+3[s Y(s)-y(0)]+2 Y(s)=0 \\
& \left(s^{2}+3 s+2\right) Y(s)=s y(0)+\left.\frac{d y}{d t}\right|_{t=0}+3 y(0) \\
& \left(s^{2}+3 s+2\right) Y(s)
\end{aligned} \begin{aligned}
& =3 s+1+9=3 s+10 \\
Y(s) & =\frac{3 s+10}{s^{2}+3 s+2}=\frac{3 s+10}{(s+1)(s+2)} \\
& =\frac{A}{s+1}+\frac{B}{s+2}
\end{aligned}
$$

$$
\begin{aligned}
& A=\left.\frac{3 s+10}{s+2}\right|_{s=-1}=7 ; \quad B=\left.\frac{3 s+10}{s+1}\right|_{s=-2}=-4 \\
& \therefore Y(s)=\frac{7}{s+1}-\frac{4}{s+2} \\
& \therefore y(t)=L^{-1}[Y(s)]=7 e^{-t}-4 e^{-2 t}=e^{-t}\left(7-4 e^{-t}\right) \\
& \therefore \text { The output of the system is } y(t)=e^{-t}\left(7-4 e^{-t}\right) u(t)
\end{aligned}
$$

Q. 5. Obtain two different realizations of the system given by
$y(n)-(a+b) y(n-1)+a b y(n-2)=x(n)$.Also obtain its transfer function.

## Ans:

$$
\begin{aligned}
& y(n)-(a+b) y(n-1)+a b y(n-2)=x(n) \\
& \quad \therefore Y(z)-(a+b) z^{-1} Y(z)+a b z^{-2} Y(z)=X(z)
\end{aligned}
$$

$$
\text { Transfer function } \mathrm{H}(\mathrm{z})=\frac{\mathrm{Y}(\mathrm{z})}{\mathrm{X}(\mathrm{z})}=\frac{1}{1-(\mathrm{a}+\mathrm{b}) \mathrm{z}^{-1}+\mathrm{ab} \mathrm{z}^{-2}}
$$

$$
y(n)=x(n)+(a+b) y(n-1)-a b y(n-2)
$$

Direct Form I/II realization
Alternative Realisation

Q. 6. An LTI system has an impulse response
$h(t)=\exp [-a t] u(t)$; when it is excited by an input signal $x(t)$, its output is $y(t)$ $=[\exp (-b t)-\exp (-c t)] u(t)$ Determine its input $x(t)$.
Ans:
$h(t)=e^{-a t} u(t)$ for input $x(t)$
Output $y(t)=\left(e^{-b t}-e^{-c t}\right) u(t)$


$$
H(s)=\frac{1}{s+a} ; Y(s)=\frac{1}{s+b}-\frac{1}{s+c}=\frac{s+c-s-b}{(s+b)(s+c)}=\frac{c-b}{(s+b)(s+c)}
$$

As $\mathrm{H}(\mathrm{s})=\frac{\mathrm{Y}(\mathrm{s})}{\mathrm{X}(\mathrm{s})}, \mathrm{X}(\mathrm{s})=\frac{\mathrm{Y}(\mathrm{s})}{\mathrm{H}(\mathrm{s})}$

$$
X(s)=\frac{(c-b)(s+a)}{(s+b)(s+c)}=\frac{A}{s+b}+\frac{B}{s+c}
$$

$$
\begin{aligned}
& A=\left.\frac{(c-b)(s+a)}{(s+c)}\right|_{s=-b}=\frac{(c-b)(-b+a)}{(-b+c)}=a-b \\
& B=\left.\frac{(c-b)(s+a)}{(s+b)}\right|_{s=-c}=\frac{(c-b)(-c+a)}{(-c+b)}=c-a \\
& \therefore X(s)=\frac{a-b}{s+b}+\frac{c-a}{s+c} \\
& X(t)=(a-b) e^{-b t}+(c-a) e^{-c t}
\end{aligned}
$$

$$
\therefore \text { The input } \mathrm{x}(\mathrm{t})=\left[(\mathrm{a}-\mathrm{b}) \mathrm{e}^{-\mathrm{bt}}+(\mathrm{c}-\mathrm{a}) \mathrm{e}^{-\mathrm{ct}}\right] \mathrm{u}(\mathrm{t})
$$

Q.7. Write an expression for the waveform $f(t)$ shown in Fig. using only unit step function and powers of $t$.

## Ans:



$$
\therefore f(t)=\frac{E}{T}[t u(t)-2(t-T) u(t-T)+2(t-3 T) u(t-3 T)-(t-4 T) u(t-4 T)]
$$

Q.8. For $f(t)$ of $Q$ 7, find and sketch $f^{\prime}(t)$ (prime denotes differentiation with respect to $t$ ).

Ans:

$$
\mathrm{f}(\mathrm{t})=\frac{\mathrm{E}}{\mathrm{~T}}[\mathrm{t} \mathrm{u}(\mathrm{t})-2(\mathrm{t}-\mathrm{T}) \mathrm{u}(\mathrm{t}-\mathrm{T})+2(\mathrm{t}-3 \mathrm{~T}) \mathrm{u}(\mathrm{t}-3 \mathrm{~T})-(\mathrm{t}-4 \mathrm{~T}) \mathrm{u}(\mathrm{t}-4 \mathrm{~T})]
$$



$$
\therefore f^{\prime}(t)=\frac{E}{T}[u(t)-2 u(t-T)+2 u(t-3 T)-u(t-4 T)]
$$

Q.9. Define a unit impulse function $\delta(\mathrm{t})$.

Ans:
Unit impulse function $\delta(t)$ is defined as:

$$
\left[\begin{array}{l}
\delta(\mathrm{t})=0, \mathrm{t} \neq 0 \\
\int_{-\infty}^{+\infty} \delta(\mathrm{t}) \mathrm{dt}=1 \\
-\infty
\end{array}\right.
$$

It can be viewed as the limit of a rectangular pulse of duration a and height $1 / \mathrm{a}$ when $a \longrightarrow 0$, as shown below.

Q.10. Sketch the function $g(t)=\frac{3}{\epsilon^{3}}(t-\epsilon)^{2}[u(t)-u(t-\epsilon)]$ and show that $\mathrm{g}(\mathrm{t}) \rightarrow \delta(\mathrm{t})$ as $\in \rightarrow 0$.
Ans:


As $\varepsilon \longrightarrow 0$, duration $\longrightarrow 0$, amplitude $\longrightarrow \infty$
$\int_{0}^{\varepsilon} g(t) d t=1$
Q.11. Show that if the FT of $x(t)$ is $X(j \omega)$, then the FT of $x\left(\frac{t}{a}\right)$ is $|a| X(j a \omega)$.

## Ans:



Let $x\left[\frac{\mathrm{t}}{\mathrm{a}}\right] \stackrel{\mathrm{a}}{\stackrel{\mathrm{FT}}{\longleftrightarrow+\infty}} \mathrm{X}_{1}(\mathrm{j} \omega)$, then

$$
\begin{aligned}
& =\int_{-\infty}^{+\infty} \mathrm{x}(\alpha) \mathrm{e}^{-\mathrm{j} \omega a \alpha} \mathrm{a} d \alpha \text { if } \mathrm{a}>0 \\
& +\infty \\
& -\int x(\alpha) \mathrm{e}^{-\mathrm{j} \omega a \alpha} \mathrm{a} d \alpha \text { if } \mathrm{a}<0 \\
& \text { Hence } X_{1}(j \omega)=|a| \int_{-\infty} x(\alpha) e^{-j \omega a \alpha} d \alpha=|a| x(j \omega a)
\end{aligned}
$$

Q.12. Solve, by using Laplace transforms, the following set of simultaneous differential equations for $\mathrm{x}(\mathrm{t})$.

Ans:

$$
\begin{aligned}
& 2 x^{\prime}(\mathrm{t})+4 \mathrm{x}(\mathrm{t})+\mathrm{y}^{\prime}(\mathrm{t})+7 \mathrm{y}(\mathrm{t})=5 \mathrm{u}(\mathrm{t}) \\
& \mathrm{x}^{\prime}(\mathrm{t})+\mathrm{x}(\mathrm{t})+\mathrm{y}^{\prime}(\mathrm{t})+3 \mathrm{y}(\mathrm{t})=5 \delta(\mathrm{t})
\end{aligned}
$$

The initial conditions are : $x(0-)=y(0-)=0$.
$2 \mathrm{x}^{\prime}(\mathrm{t})+4 \mathrm{x}(\mathrm{t})+\mathrm{y}^{\prime}(\mathrm{t})+7 \mathrm{y}(\mathrm{t})=5 \mathrm{u}(\mathrm{t})$

$$
\begin{aligned}
& \mathrm{x}^{\prime}(\mathrm{t})+\mathrm{x}(\mathrm{t})+\mathrm{y}^{\prime}(\mathrm{t})+3 \mathrm{y}(\mathrm{t})=5 \delta(\mathrm{t}) \\
& \mathrm{x}(\mathrm{t}) \stackrel{\mathrm{L}}{\longleftrightarrow} \mathrm{X}(\mathrm{~s}), \mathrm{x}^{\prime}(\mathrm{t}) \stackrel{\mathrm{L}}{\longleftrightarrow} \mathrm{~s} \mathrm{X}(\mathrm{~s}), \delta(\mathrm{t}) \stackrel{\mathrm{L}}{\longleftrightarrow} 1, \mathrm{u}(\mathrm{t}) \stackrel{\mathrm{L}}{\longleftrightarrow} \underline{1}
\end{aligned}
$$

(Given zero initial conditions)

$$
\begin{aligned}
& \therefore 2 \mathrm{sX}(\mathrm{~s})+4 \mathrm{X}(\mathrm{~s})+\mathrm{sY}(\mathrm{~s})+7 \mathrm{Y}(\mathrm{~s})=\underline{5} \\
& \mathrm{~s} \\
& \mathrm{sX}(\mathrm{~s})+\mathrm{X}(\mathrm{~s})+\mathrm{sY}(\mathrm{~s})+3 \mathrm{Y}(\mathrm{~s})=5 \\
& (2 \mathrm{~s}+4) \mathrm{X}(\mathrm{~s})+(\mathrm{s}+7) \mathrm{Y}(\mathrm{~s})=\underline{5} \\
& (\mathrm{~s}+1) \mathrm{X}(\mathrm{~s})+(\mathrm{s}+3) \mathrm{Y}(\mathrm{~s})=5 \\
& \mathrm{X}(\mathrm{~s})=\left|\begin{array}{cc}
\frac{5}{s} & \mathrm{~s}+7 \\
\mathrm{~S} & 3 \\
5 & \mathrm{~s}+3
\end{array}\right| \\
& \left|\begin{array}{cc}
2 \mathrm{~s}+4 & \mathrm{~s}+7 \\
\mathrm{~s}+1 & \mathrm{~s}+3
\end{array}\right|
\end{aligned}
$$

$$
\begin{aligned}
\text { Or, } & X(s)=-\frac{5 s+35-5-15 / \mathrm{s}}{2 s^{2}+6 s+4 s+12-s^{2}-8 s-7} \\
& =-\frac{5 s^{2}+30 s-15}{s\left(s^{2}+2 s+5\right)}=-\frac{5}{s}\left(\frac{s^{2}+6 s-3}{s^{2}+2 s+5}\right)=\frac{A}{s}+\frac{B s+C}{s^{2}+2 s+5}
\end{aligned}
$$

Then $\mathrm{A}\left(\mathrm{s}^{2}+2 \mathrm{~s}+5\right)+\mathrm{B} \mathrm{s}^{2}+\mathrm{Cs}=-5\left(\mathrm{~s}^{2}+6 \mathrm{~s}-3\right)$
$\therefore \mathrm{A}+\mathrm{B}=-5$

$$
\begin{aligned}
& 2 \mathrm{~A}+\mathrm{C}=-30 \\
& 5 \mathrm{~A}=15
\end{aligned}
$$

Thus $\mathrm{A}=3, \mathrm{~B}=-8, \mathrm{C}=-36$ and we can write

$$
\left.\begin{array}{l}
X(s)=\underline{3}-\frac{8}{s}(\mathrm{~s}+1 \\
\therefore \mathrm{x}+1)^{2}+2^{2}
\end{array}-14 \frac{2}{(\mathrm{~s}+1)^{2}+2^{2}}=\left(3-8 \mathrm{e}^{-\mathrm{t}} \cos 2 \mathrm{t}-14 \mathrm{e}^{-\mathrm{t}} \sin 2 \mathrm{t}\right) \mathrm{u}(\mathrm{t}) \mathrm{t}\right)
$$

Q.13. Find the Laplace transform of $t \sin \omega_{0} t u(t)$.

## Ans:


$\mathrm{L}\left[\mathrm{t} \sin \left(\omega_{0} \mathrm{t}\right) \mathrm{u}(\mathrm{t})\right]=-\frac{\mathrm{d}}{\mathrm{ds}}\left[\frac{\omega_{0}}{\mathrm{~s}^{2}+\omega_{0}{ }^{2}}\right]$
$=\left[\frac{0-\omega_{0}(2 \mathrm{~s})}{\left(\mathrm{s}^{2}+\omega_{0}{ }^{2}\right)^{2}}\right]=\frac{2 \omega_{0} \mathrm{~s}}{\left(\mathrm{~s}^{2}+\omega_{0}{ }^{2}\right)^{2}}$
Q.14. Find the inverse Laplace transform of $\frac{s-2}{s(s+1)^{3}}$.

Ans:

$$
\begin{aligned}
& F(s)=\frac{s-2}{s(s+1)^{3}}=\frac{A}{s}+\frac{\mathrm{B}}{\mathrm{~s}+1}+\frac{\mathrm{C}}{(\mathrm{~s}+1)^{2}}+\frac{\mathrm{D}}{(\mathrm{~s}+1)^{3}} \\
& \mathrm{~A}=\frac{\mathrm{s}-2}{\left.(\mathrm{~s}+1)^{3}\right|_{\mathrm{s}=0}=-2} \begin{array}{ll}
\mathrm{A}(\mathrm{~s}+1)^{3}+\mathrm{Bs}(\mathrm{~s}+1)^{2}+\mathrm{Cs}(\mathrm{~s}+1)+\mathrm{Ds}=\mathrm{s}-2 \\
\mathrm{D}=\left.\frac{\mathrm{s}-2}{\mathrm{~s}}\right|_{\mathrm{s}=-1}=3 & \mathrm{~s}^{3}: \mathrm{A}+\mathrm{B}=0 \\
\mathrm{~A}=-2 & \mathrm{~s}^{2}: 3 \mathrm{~A}+2 \mathrm{~B}+\mathrm{C}=0
\end{array} \\
& \mathrm{D}=3
\end{aligned}
$$

$$
\begin{aligned}
& F(s)=\frac{-2}{s}+\frac{2}{s+1}+\frac{2}{(s+1)^{2}}+\frac{3}{(s+1)^{3}} \\
& \therefore f(t)=-2+2 e^{-t}+2 t e^{-t}+\underline{3} t^{2} e^{-t} \\
& \therefore f(t)=\left[-2+e^{-t}\left(\frac{3}{2} t^{2}+2 t+2\right)\right] u(t)
\end{aligned}
$$

Q.15. Show that the difference equation $y(n)-\alpha y(n-1)=-\alpha x(n)+x(n-1)$ represents an all-pass transfer function. What is (are) the condition(s) on $\alpha$ for the system to be stable?
Ans:

$$
\begin{aligned}
& y(n)-\alpha y(n-1)=-\alpha x(n)+x(n-1) \\
& Y(z)-\alpha Z^{-1} Y(z)=-\alpha X(z)+z^{-1} X(z) \\
& \left(1-\alpha z^{-1}\right) Y(z)=\left(-\alpha+z^{-1}\right) X(z) \\
& H(z)=\frac{Y(z)}{X(z)}=\frac{-\alpha+z^{-1}}{1-\alpha z^{-1}}=\frac{1-\alpha z}{z-\alpha}
\end{aligned}
$$

| Zero : $\mathrm{Z}=\underline{1}$ | $\begin{array}{l}\text { As poles and zeros have reciprocal values, the transfer function } \\ \text { represents an all pass filter system. }\end{array}$ |
| :---: | :--- |

Pole : $\mathrm{z}=\alpha$

## Condition for stability of the system :

For stability, the pole at $\mathrm{z}=\alpha$ must be inside the unit circle, i.e. $|\alpha|<1$.
Q.16. Give a recursive realization of the transfer function $H(z)=1+z^{-1}+z^{-2}+z^{-3}$

## Ans:

$$
\mathrm{H}(\mathrm{z})=1+\mathrm{z}^{-1}+\mathrm{z}^{-2}+\mathrm{z}^{-3}=\frac{1-\mathrm{z}^{-4}}{1-\mathrm{z}^{-1}}\binom{\text { Geometric series of } 4 \text { terms }}{\text { First term }=1, \text { Common ratio }=\mathrm{z}^{-1}}
$$

As $H(z)=\frac{Y(z)}{X(z)}$, we can write
$\therefore\left(1-\mathrm{z}^{-1}\right) \mathrm{Y}(\mathrm{z})=\left(1-\mathrm{z}^{-4}\right) \mathrm{X}(\mathrm{z})$ or $\mathrm{Y}(\mathrm{z})=\frac{\mathrm{X}(\mathrm{z})}{\left(1-\mathrm{z}^{-1}\right)}\left(1-\mathrm{z}^{-4}\right)=\mathrm{W}(\mathrm{z})\left(1-\mathrm{z}^{-4}\right)$
The realization of the system is shown below.

Q. 17 Determine the z-transform of $\mathrm{x}_{1}(\mathrm{n})=\alpha^{\mathrm{n}} \mathrm{u}(\mathrm{n})$ and $\mathrm{x}_{2}(\mathrm{n})=-\alpha^{\mathrm{n}} \mathrm{u}(-\mathrm{n}-1)$ and indicate their regions of convergence.

Ans:

$$
\begin{aligned}
& \mathrm{x}_{1}(\mathrm{n})=\alpha^{\mathrm{n}} \mathrm{u}(\mathrm{n}) \quad \text { and } \quad \mathrm{x}_{2}(\mathrm{n})=-\alpha^{\mathrm{n}} \mathrm{u}(-\mathrm{n}-1) \\
& X_{1}(z)=\frac{1}{1-\alpha Z^{-1}} \operatorname{RoC}\left|\alpha z^{-1}\right|<1 \text { i.e., }|z|>\alpha \\
& X_{2}(z)=\sum_{n=-\infty}^{-1}-\alpha^{n} z^{-n} \\
& =-\sum_{\mathrm{n}=1}^{\infty} \alpha^{-\mathrm{n}} z^{\mathrm{n}}=-\left(\alpha^{-1} z+\alpha^{-2} z^{2}+\alpha^{-3} z^{3}+\ldots \ldots \ldots\right) \\
& =-\alpha^{-1} z\left(1+\alpha^{-1} z+\alpha^{-2} z^{2}+\ldots \ldots . .\right) \\
& =\frac{-\alpha^{-1} \mathrm{z}}{1-\alpha^{-1} \mathrm{z}}=\frac{\mathrm{z}}{\mathrm{z}-\alpha}=\frac{1}{1-\alpha \mathrm{z}^{-1}} ; \quad \operatorname{RoC} \quad\left|\alpha^{-1} \mathrm{z}\right|<1 \text { i.e., }|\mathrm{z}|<|\alpha|
\end{aligned}
$$

Q.18. Determine the sequence $h(n)$ whose z-transform is

$$
\begin{equation*}
\mathrm{H}(\mathrm{z})=\frac{1}{1-2 \mathrm{r} \cos \theta \mathrm{z}^{-1}+\mathrm{r}^{2} \mathrm{z}^{-2}}, \quad|\mathrm{r}|<1 \tag{6}
\end{equation*}
$$

Ans:

$$
\begin{aligned}
\mathrm{H}(\mathrm{z}) & =\frac{1}{1-2 \mathrm{recos} \theta^{-1}+\mathrm{r}^{2} \mathrm{z}^{-2}}, \quad|\mathrm{r}|<1 \\
& =\frac{1}{\left(1-\mathrm{re}^{\mathrm{j} \theta} \mathrm{z}^{-1}\right)\left(1-\mathrm{re}^{-\mathrm{j} \theta} \mathrm{z}^{-1}\right)}, \quad|\mathrm{r}|<1 \\
& =\frac{\mathrm{A}}{\left(1-\mathrm{re}^{\mathrm{j} \theta} \mathrm{z}^{-1}\right)}+\frac{\mathrm{B}}{\left(1-\mathrm{re}^{-\mathrm{j} \theta} \mathrm{z}^{-1}\right)}=|\mathrm{r}|<1
\end{aligned}
$$

$$
\begin{aligned}
& \text { where } A=\quad \frac{1}{\left(1-\mathrm{re}^{1 \theta} z^{-1}\right)} \left\lvert\, r \mathrm{e}^{\mathrm{j} \mathrm{\theta} \mathrm{z}^{-1}=1}=\frac{1}{1-e^{-j 2 \theta}}\right. \\
& B=\left.\quad \frac{1}{\left(1-r e^{j \theta} z^{-1}\right)}\right|_{r e^{-j \theta} z^{-1}=1}=\frac{1}{1-e^{j 2 \theta}} \\
& \therefore \mathrm{~h}(\mathrm{n})=\frac{1}{1-\mathrm{e}^{-2 \mathrm{j} \theta}}\left(\mathrm{re}^{\mathrm{j} \theta}\right)^{\mathrm{n}}+\frac{1}{1-\mathrm{e}^{2 \mathrm{j} \theta}}\left(\mathrm{re}^{-\mathrm{j} \theta}\right)^{\mathrm{n}} \\
& \therefore \mathrm{~h}(\mathrm{n})=\mathrm{r}^{\mathrm{n}}\left[\frac{e^{j^{n \theta}}}{1-e^{-j 2 \theta}}+\frac{e^{-j n \theta}}{1-e^{j 2 \theta}}\right] \mathrm{u}(\mathrm{n}) \\
& =r^{n} \frac{e^{j(n+1) \theta}-e^{-j(n+1) \theta}}{e^{j \theta}-e^{-j \theta}} u(n) \\
& =\frac{\mathrm{r}^{\mathrm{n}} \sin (\mathrm{n}+1) \theta}{\sin \theta} \mathrm{u}(\mathrm{n})
\end{aligned}
$$

Q.19. Let the $Z$ - transform of $x(n)$ be $X(z)$.Show that the $z$-transform of $x(-n)$ is $X\left(\frac{1}{z}\right)$.

Ans:


Then $Y(z)=\sum_{n=-\infty}^{\infty} x(-n) z^{-n}=\sum_{r=-\infty}^{\infty} x(r) z^{+r}=\sum_{r=-\infty}^{\infty} x(r)\left(z^{-1}\right)^{-1}=X\left(z^{-1}\right)$
Q.20. Find the energy content in the signal $x(n)=e^{-n / 10} \sin \left(\frac{2 \pi n}{4}\right)$.

Ans:

$$
\begin{aligned}
& x(n)=e^{-0.1 n} \sin \left(\frac{2 \pi n}{4}\right) \\
& \text { Energy content } E=\sum_{n=-\infty}^{+\infty}\left|x^{2}(n)\right|=\sum_{n=-\infty}^{+\infty} e^{-0.2 n}\left(\sin \left(\frac{2 \pi n}{4}\right)\right)^{2} \\
& E=\sum_{n=-\infty}^{+\infty} \mathrm{e}^{-2 n} \sin ^{2} \frac{\mathrm{n} \pi}{2} \\
& E=\sum_{n=-\infty}^{+\infty} \mathrm{e}^{-2 \mathrm{n}} \quad \frac{1-\cos n \pi}{2} \\
& =\frac{1}{2} \sum_{n=-\infty}^{+\infty} \mathrm{e}^{-2 n}\left[1-(-1)^{n}\right]
\end{aligned}
$$

Now $1-(-1)^{n}=\left\{\begin{array}{l}2 \text { for } n \text { odd } \\ 0 \text { for } n \text { even }\end{array}\right.$
Also Let $\mathrm{n}=2 \mathrm{r}+1$; then $\quad \mathrm{E}=\sum_{\mathrm{r}=-\infty}^{\infty} \mathrm{e}^{--2(2 \mathrm{r}+1)}=\sum_{\mathrm{r}=-\infty}^{\infty} \mathrm{e}^{-4 \mathrm{r}} \mathrm{e}^{-.2}$
$=\mathrm{e}^{-. .2}\left(\sum_{\mathrm{r}=0}^{\infty} \mathrm{e}^{-.4 \mathrm{r}}+\sum_{\mathrm{r}=1}^{\infty} \mathrm{e}^{-4 \mathrm{r}}\right) \quad \underset{\text { E is infinite. }}{\text { The second term in brackets goes to infinity } . \text { Hence }}$
Q.21. Sketch the odd part of the signal shown in Fig.

## Ans:



Odd part $\quad x_{0}(t)=\frac{x(t)-x(-t)}{2}$

Q.22. A linear system H has an input-output pair as shown in Fig. Determine whether the system is causal and time-invariant.

Ans


System is non-causal * the output $\mathrm{y}(\mathrm{t})$ exists at $\mathrm{t}=0$ when input $\mathrm{x}(\mathrm{t})$ starts only at

$$
\mathrm{t}=+1 .
$$

System is time-varying . the expression for $\mathrm{y}(\mathrm{t})=[\mathrm{u}(\mathrm{t})-\mathrm{u}(\mathrm{t}-1)(\mathrm{t}-1)+\mathrm{u}(\mathrm{t}-3)(\mathrm{t}-3)$ $-u(t-3)]$ shows that the system $H$ has time varying parameters.
Q.23. Determine whether the system characterized by the differential equation

$$
\begin{equation*}
\frac{\mathrm{d}^{2} \mathrm{y}(\mathrm{t})}{\mathrm{dt}^{2}}-\frac{\mathrm{dy}(\mathrm{t})}{\mathrm{dt}}+2 \mathrm{y}(\mathrm{t})=\mathrm{x}(\mathrm{t}) \text { is stable or not. } \tag{4}
\end{equation*}
$$

Ans:

$$
\frac{\mathrm{d}^{2} y(\mathrm{t})}{\mathrm{dt}^{2}}-\frac{\mathrm{dy}(\mathrm{t})}{\mathrm{dt}}+2 \mathrm{y}(\mathrm{t})=\mathrm{x}(\mathrm{t})
$$

$\mathrm{L} \quad \mathrm{L}$
$\mathrm{y}(\mathrm{t}) \longleftrightarrow \mathrm{Y}(\mathrm{s}) ; \mathrm{x}(\mathrm{t}) \longleftrightarrow \mathrm{X}(\mathrm{s}) ;$ Zero initial conditions
$\mathrm{s}^{2} \mathrm{Y}(\mathrm{s})-\mathrm{sY}(\mathrm{s})+2 \mathrm{Y}(\mathrm{s})=\mathrm{X}(\mathrm{s})$
System transfer function $\frac{Y(s)}{X(s)}=\frac{1}{s^{2}-s+2}$ whose poles are in the right half plane.
Hence the system is not stable.
Q. 24 Determine whether the system $\mathrm{y}(\mathrm{t})=\int_{-\infty}^{\mathrm{t}} \mathrm{x}(\tau) \mathrm{d} \tau$ is invertible.

Ans:

$$
\mathrm{y}(\mathrm{t})=\int_{-\infty}^{\mathrm{t}} \mathrm{x}(\tau) \mathrm{d} \tau
$$

Condition for invertibility: $\quad \mathrm{H}^{-1} \mathrm{H}=\mathrm{I}$ (Identity operator)

$$
\begin{aligned}
& \left\{\begin{array}{r}
\mathrm{H} \longrightarrow \text { Integration } \\
\mathrm{H}^{-1} \longrightarrow \text { Differentiation }
\end{array}\right. \\
& \mathrm{x}(\mathrm{t}) \longrightarrow \mathrm{y}(\mathrm{t})=\mathrm{H}\{\mathrm{x}(\mathrm{t})\}
\end{aligned}
$$

The system is invertible.
Q. 25 Find the impulse response of a system characterized by the differential equation

$$
\begin{equation*}
y^{\prime}(t)+a y(t)=x(t) . \tag{5}
\end{equation*}
$$

Ans:

$$
\begin{aligned}
& y^{\prime}(\mathrm{t})+\mathrm{a} \mathrm{y}(\mathrm{t})=\mathrm{x}(\mathrm{t}) \\
& \mathrm{x}(\mathrm{t}) \stackrel{\mathrm{L}}{\longleftrightarrow} \mathrm{X}(\mathrm{~s}), \mathrm{y}(\mathrm{t}) \stackrel{\mathrm{L}}{\longleftrightarrow} \mathrm{Y}(\mathrm{~s}), \mathrm{h}(\mathrm{t}) \stackrel{\mathrm{L}}{\longleftrightarrow} \mathrm{H}(\mathrm{~s})
\end{aligned}
$$

$\mathrm{sY}(\mathrm{s})+\mathrm{aY}(\mathrm{s})=\mathrm{X}(\mathrm{s})$, assuming zero initial conditions

$$
\mathrm{H}(\mathrm{~s})=\frac{\mathrm{Y}(\mathrm{~s})}{\mathrm{X}(\mathrm{~s})}=\frac{1}{\mathrm{~s}+\mathrm{a}}
$$

$\therefore$ The impulse response of the system is $h(t)=e^{-a t} u(t)$
Q.26. Compute the Laplace transform of the signal $y(t)=(1+0.5 \sin t) \sin 1000 t$.

Ans:

$$
\begin{aligned}
y(t)= & (1+0.5 \operatorname{sint}) \sin 1000 t \\
& =\sin 1000 t+0.5 \operatorname{sint} \sin 1000 t \\
& =\sin 1000 t+0.5\left[\frac{\cos 999 t-\cos 1001 t}{2}\right) \\
& =\sin 1000 t+0.25 \cos 999 t-0.25 \cos 1001 \mathrm{t} \\
\therefore & Y(s)=\frac{1000}{\mathrm{~s}^{2}+1000^{2}}+0.25 \frac{\mathrm{~s}}{\mathrm{~s}^{2}+999^{2}}-0.25 \frac{\mathrm{~s}}{\mathrm{~s}^{2}+1001^{2}}
\end{aligned}
$$

Q.27. Determine Fourier Transform $F(\omega)$ of the signal $f(t)=e^{-\alpha t} \cos (\omega t+\theta)$ and determine the value of $|F(\omega)|$.

Ans:
We assume $f(t)=e^{-\alpha t} \cos (\omega t+\theta) u(t)$ because otherwise FT does not exist

$$
\begin{aligned}
& f(t) \stackrel{F T}{\longleftrightarrow} F(\omega)=\int^{+\infty} e^{-\alpha t} \frac{\left.e^{j(\omega t+\theta)}+e^{-j(\omega t}+\theta\right)}{2} e^{-j \omega t} d t \\
& \therefore F(\omega)=\frac{1}{2} \int^{+\infty}\left[e^{-\alpha t} e^{-j \omega t} e^{j \omega t+j \theta}+e^{-\alpha t} e^{-j \omega t} e^{-j \omega t-j \theta}\right] d t \\
& =\frac{1}{2} \int^{+\infty}\left[\mathrm{e}^{-\alpha t+j \theta}+\mathrm{e}^{-\mathrm{j} \theta} \mathrm{e}^{-(\alpha+2 j \omega) t}\right] \mathrm{dt} \\
& |\mathrm{~F}(\omega)|=\frac{1}{2}\left|\mathrm{e}^{\mathrm{j} \theta} \frac{\mathrm{e}^{-\alpha \mathrm{t}}}{-\alpha}\right|_{0}^{+\infty}+\left.\mathrm{e}^{-\mathrm{j} \theta} \frac{\mathrm{e}^{-(\alpha+2 \mathrm{j} \omega) \mathrm{t}}}{-(\alpha+2 \mathrm{j} \omega)}\right|_{0} ^{\omega} \\
& =\frac{1}{2}\left|\frac{1}{\alpha} \mathrm{e}^{\mathrm{j} \theta}+\frac{1}{\alpha+2 \mathrm{j} \omega} \mathrm{e}^{-\mathrm{j} \theta}\right| \\
& \cdot|F(\omega)|=\frac{1}{2}\left|\frac{(\alpha+2 j \omega) \mathrm{e}^{\mathrm{j} \theta}+\alpha \mathrm{e}^{-\mathrm{j} \theta}}{\alpha(\alpha+2 \mathrm{j} \omega)}\right| \\
& =\quad \frac{1}{2}\left|\frac{2 \alpha \cos \theta+2 \mathrm{j} \omega \mathrm{e}^{\mathrm{j} \theta}}{\alpha(\alpha+2 \mathrm{j} \omega)}\right| \\
& =\quad\left|\frac{\alpha \cos \theta+\mathrm{j} \omega \cos \theta-\mathrm{j} \omega \sin \theta}{\alpha(\alpha+2 \mathrm{j} \omega)}\right|
\end{aligned}
$$

$$
\begin{aligned}
& |\mathrm{F}(\omega)|^{2}=\frac{\alpha^{2} \cos ^{2} \theta+\omega^{2}-2 \alpha \omega \sin \theta+\cos \theta}{\alpha^{2}\left(\alpha^{2}+4 \omega^{2}\right)} \\
& =\quad \frac{\omega^{2}+\alpha^{2} \cos ^{2} \theta-\alpha \omega \sin 2 \theta}{\alpha^{2}\left(\alpha^{2}+4 \omega^{2}\right)}
\end{aligned}
$$

Q.28. Determine the impulse response $h(t)$ and sketch the magnitude and phase
response of the system described by the transfer function

$$
\mathrm{H}(\mathrm{~s})=\frac{\mathrm{s}^{2}+\omega_{\mathrm{o}}^{2}}{\mathrm{~s}^{2}+\frac{\omega_{\mathrm{o}}}{\mathrm{Q}} \mathrm{~s}+\omega_{\mathrm{o}}^{2}} .
$$

Ans:

$$
\operatorname{Arg} H(j \omega)=-\tan ^{-1}\left(\frac{\omega\left[\underline{\omega_{0}}\right]}{\omega_{0}{ }^{2}-\omega^{2}}\right)
$$

| $\omega$ | $\mathrm{H}(\mathrm{j} \omega)$ | $\operatorname{Arg} \mathrm{H}(\mathrm{j} \omega)$ |
| :---: | :---: | :---: |
| 0 | 1 | 0 |
| $\infty$ | 1 | 0 |
| $\omega_{0-}$ | 0 | $-\pi / 2$ |
| $\omega_{0+}$ | 0 | $+\pi / 2$ |



$$
\begin{aligned}
& \mathrm{H}(\mathrm{~s})=\begin{array}{c}
\mathrm{s}^{2}+\omega_{0}{ }^{2} \\
\mathrm{~s}^{2}+\underline{\omega}_{0} \mathrm{~s}+\omega_{0}{ }^{2}
\end{array} \\
& \text { Q } \\
& H(j \omega)=\frac{(j \omega)^{2}+\omega_{0}{ }^{2}}{(j \omega)^{2}+\underline{\omega_{0}}(j \omega)+\omega_{0}{ }^{2}}=\frac{\omega_{0}{ }^{2}-\omega^{2}}{\omega_{0}{ }^{2}-\omega^{2}+j \omega \underline{\omega_{0}}} \\
& \therefore|\mathrm{H}(\mathrm{j} \omega)|=\frac{\left|\omega_{0}{ }^{2}-\omega^{2}\right|}{\left|\left(\omega_{0}{ }^{2}-\omega^{2}\right)^{2}+\omega^{2}\left(\frac{\omega_{0}}{}{ }^{2}\right]\right|^{1 / 2}}
\end{aligned}
$$

Q.29. Using the convolution sum, determine the output of the digital system shown in Fig. below.

Assume that the input sequence is $\{\mathrm{x}(\mathrm{n})\}=\{3,-1,3\}$ and that the system is initially at rest.


Ans:

$\mathrm{x}(\mathrm{n})=3 \delta(\mathrm{n})-\delta(\mathrm{n}-1)+3 \delta(\mathrm{n}-2)$
$\mathrm{X}(\mathrm{z})=3-\mathrm{z}^{-1}+3 \mathrm{z}^{-2}$
Digital system: $\mathrm{y}(\mathrm{n})=\mathrm{x}(\mathrm{n})+\frac{1}{2} \mathrm{y}(\mathrm{n}-1)$
$\therefore \mathrm{Y}(\mathrm{z})=\frac{\mathrm{X}(\mathrm{z})}{1-\frac{1}{2} \mathrm{z}^{-1}}=\frac{2}{\frac{3-\mathrm{z}^{-1}+3 \mathrm{z}^{-2}}{1-\frac{1}{2} \mathrm{z}^{-1}}}=-10-6 \mathrm{z}^{-1}+\frac{13}{1-\frac{1}{2} \mathrm{z}^{-1}}$
by partial fraction expansion.
Hence $\mathrm{y}(\mathrm{n})=-10 \delta(\mathrm{n})-6 \delta(\mathrm{n}-1)+13\left(\frac{1}{2}\right)^{\mathrm{n}} \mathrm{u}(\mathrm{n})$
Q.30. Find the z-transform of the digital signal obtained by sampling the analog signal

$$
\begin{equation*}
\mathrm{e}^{-4 \mathrm{t}} \sin 4 \mathrm{t} \mathrm{u}(\mathrm{t}) \text { at intervals of } 0.1 \mathrm{sec} . \tag{6}
\end{equation*}
$$

Ans:

$$
\mathrm{x}(\mathrm{t})=\mathrm{e}^{-4 \mathrm{t}} \sin 4 \mathrm{t} \mathrm{u}(\mathrm{t}), \quad \mathrm{T}=0.1 \mathrm{~s}
$$

$$
\begin{array}{l|l}
\mathrm{x}(\mathrm{n})=\mathrm{x}(\mathrm{t} \longleftrightarrow \mathrm{nT})=\mathrm{x}(0.1 \mathrm{n})=\left(\mathrm{e}^{-0.4}\right)^{\mathrm{n}} \sin (0.4 \mathrm{n}) \\
\mathrm{x}(\mathrm{n}) \stackrel{\mathrm{z}}{\longleftrightarrow} \mathrm{X}(\mathrm{z}) \\
\mathrm{x}(\mathrm{n})=\sin \Omega \mathrm{n}(\mathrm{n}) \stackrel{\mathrm{z}}{\longleftrightarrow} & \begin{array}{l}
\alpha=\mathrm{e}^{-0.4}=0.6703, \underline{1}=1.4918 \\
\alpha
\end{array} \\
\frac{\mathrm{z} \sin \Omega}{\mathrm{z}^{2}-2 \mathrm{z} \cos \Omega+1} & \begin{array}{l}
\Omega=0.4 \mathrm{rad}=22.92^{\circ} \\
\sin \Omega=0.3894 ; \cos \Omega=0.9211
\end{array}
\end{array}
$$

$$
\begin{aligned}
& \alpha^{\mathrm{n}} \mathrm{X}(\mathrm{n}) \stackrel{\mathrm{z}}{\longleftrightarrow} \mathrm{X}(\mathrm{z} / \alpha) \\
& \therefore \mathrm{X}(\mathrm{z})=\frac{1.4918 \mathrm{z}(0.3894)}{(1.4918)^{2} \mathrm{z}^{2}-2(1.4918) \mathrm{z}(0.9211)+1} \\
& \mathrm{X}(\mathrm{z})=\frac{0.5809 \mathrm{z}}{2.2255 \mathrm{z}^{2}-2.7482 \mathrm{z}+1}
\end{aligned}
$$

Q.31. An LTI system is given by the difference equation $y(n)+2 y(n-1)+y(n-2)=x(n)$.
i. Determine the unit impulse response.
ii. Determine the response of the system to the input $(3,-1,3)$.

$$
\begin{gather*}
\uparrow  \tag{4}\\
\mathrm{n}=0
\end{gather*}
$$

Ans:
$\mathrm{y}(\mathrm{n})+2 \mathrm{y}(\mathrm{n}-1)+\mathrm{y}(\mathrm{n}-2)=\mathrm{x}(\mathrm{n})$
$\mathrm{Y}(\mathrm{z})+2 \mathrm{z}^{-1} \mathrm{Y}(\mathrm{z})+\mathrm{z}^{-2} \mathrm{Y}(\mathrm{z})=\mathrm{X}(\mathrm{z})$
$\left(1+2 \mathrm{z}^{-1}+\mathrm{z}^{-2}\right) \mathrm{Y}(\mathrm{z})=\mathrm{X}(\mathrm{z})$
(i). $\mathrm{H}(\mathrm{z})=\frac{\mathrm{Y}(\mathrm{z})}{\mathrm{X}(\mathrm{z})}=\frac{1}{1+2 \mathrm{z}^{-1}+\mathrm{z}^{-2}}=\frac{1}{\left(1+\mathrm{z}^{-1}\right)^{2}} \quad$ (Binomial expansion)
$=1-2 \mathrm{z}^{-1}+3 \mathrm{z}^{-2}-4 \mathrm{z}^{-3}+5 \mathrm{z}^{-4}-6 \mathrm{z}^{-5}+7 \mathrm{z}^{-6}-\ldots \ldots$. (Binomial expansion)
$\therefore \mathrm{h}(\mathrm{n})=\delta(\mathrm{n})-2 \delta(\mathrm{n}-1)+3 \delta(\mathrm{n}-2)-\ldots .$. $=\{1,-2,3,-4,5,-6,7, \ldots$.$\} is the impulse response.$
(ii). $x(n)=\{\underbrace{3,-1,3\}}_{n=0}$

$$
=3 \delta(\mathrm{n})-\delta(\mathrm{n}-1)+3 \delta(\mathrm{n}-2)
$$

$\mathrm{X}(\mathrm{z})=3-\mathrm{z}^{-1}+3 \mathrm{z}^{-2}$

$$
\begin{aligned}
\therefore Y(z) & =X(z) \cdot H(z)=\frac{3-z^{-1}+3 z^{-2}}{1+2 z^{-1}+z^{-2}}=\frac{3\left(1+2 z^{-1}+z^{-2}\right)-7 z^{-1}}{1+2 z^{-1}+z^{-2}} \\
& =3-7 \frac{z^{-1}}{\left(1+z^{-1}\right)^{2}}
\end{aligned}
$$

$\therefore \mathrm{y}(\mathrm{n})=3 \delta(\mathrm{n})+7 \mathrm{nu}(\mathrm{n})$ is the required response of the system.
Q.32. The signal $x(t)$ shown below in Fig. is applied to the input of an
(i) ideal differentiator.
(ii) ideal integrator.

Sketch the responses.
$\mathrm{x}(\mathrm{t})=\mathrm{tu}(\mathrm{t})-3 \mathrm{t} \mathrm{u}(\mathrm{t}-1)+2 \mathrm{t} \mathrm{u}(\mathrm{t}-1.5)$


Ans:

(ii) $1<\mathrm{t}<1.5$
$\mathrm{y}(\mathrm{t})=\mathrm{y}(1)+\int^{\mathrm{t}}(3-2 \mathrm{t}) \mathrm{dt}$
1
$=0.5+\left(3 t-t^{\mathrm{t}}\right)=0.5+3 \mathrm{t}-\mathrm{t}^{2}-3+1$
$=3 \mathrm{t}-\mathrm{t}^{2}-1.5 \quad$ (Nonlinear)
For $\mathrm{t}=1: \mathrm{y}(1)=3-1-1.5=0.5$
(iii) $\mathrm{t} \geq 1.5: \mathrm{y}(1.5)=4.5-2.25-1.5=0.75$
Q.33. Sketch the even and odd parts of
(i) a unit impulse function
(ii) a unit step function
(iii) a unit ramp function.

Ans:
Even part $\quad x_{e}(t)=\frac{x(t)+x(-t)}{2}$
Odd part $\quad \mathrm{x}_{\mathrm{o}}(\mathrm{t})=\frac{\mathrm{x}(\mathrm{t})-\mathrm{x}(-\mathrm{t})}{2}$

(i) unit impulse function

(ii) unit step
function

(iii) unit ramp
function
Q.34. Sketch the function $\mathrm{f}(\mathrm{t})=\mathrm{u}\left(\sin \frac{\pi \mathrm{t}}{\mathrm{T}}\right)-\mathrm{u}\left(-\sin \frac{\pi \mathrm{t}}{\mathrm{T}}\right)$.

Ans:

$f(t)=\left\{\begin{array}{cl}1 & 0<t \mathrm{~T}, 2 \mathrm{~T}<\mathrm{t} 3 \mathrm{~T} 1 \\ -1 & \mathrm{~T}<\mathrm{t} 2 \mathrm{~T}, \ldots \\ 3 & \mathrm{~T}<\mathrm{t}<4 \mathrm{~T}, \ldots \ldots .\end{array}\right.$
Q.35. Under what conditions, will the system characterized by $y(n)=\sum_{k=n_{o}}^{\infty} e^{-a k} x(n-k)$ be linear, time-invariant, causal, stable and memory less?
Ans:
$\mathrm{y}(\mathrm{n})$ is : linear and time invariant for all k
causal if $\mathrm{n}_{0}$ not less than 0 .
stable if a>0
memoryless if $\mathrm{k}=0$ only
Q.36. Let E denote the energy of the signal $\mathrm{x}(\mathrm{t})$. What is the energy of the signal $x(2 t)$ ?

## Ans:

Given that
$\mathrm{E}=\int_{-\infty}^{\infty}|x(t)|^{2} \mathrm{dt}$
To find $\mathrm{E}^{1}=\int_{-\infty}^{\infty}|x(2 t)|^{2} d t$
Let $2 \mathrm{t}=\mathrm{r}$ then $\mathrm{E}^{1}=\int_{-\infty}^{\infty}|x(r)|^{2} \frac{d r}{2}=\frac{1}{2} \int_{-\infty}^{\infty}|x(r)|^{2} d r=\frac{E}{2}$
Q.37. $x(n), h(n)$ and $y(n)$ are, respectively, the input signal, unit impulse response and output signal of a linear, time-invariant, causal system and it is given that $y(n-2)=x\left(n-n_{1}\right) * h\left(n-n_{2}\right)$, where $*$ denotes convolution. Find the possible sets of values of $\mathrm{n}_{1}$ and $\mathrm{n}_{2}$.
Ans:

$$
\begin{gathered}
y(n-2)=x\left(n-n_{1}\right) * h\left(n-n_{2}\right) \\
z^{-2} Y(z)=z^{-n 1} X(z) z^{-n 2} H(z) \\
z^{-2} H(z) X(z)=z^{-\left(n_{1}+n_{2}\right)} X(z) H(z) \\
\therefore n_{1}+n_{2}=2
\end{gathered}
$$

Also, $n_{1}, n_{2} \geq 0$, as the system is causal. So, the possible sets of values for $n_{1}$ and $n_{2}$ are:

$$
\left\{\mathrm{n}_{1}, \mathrm{n}_{2}\right\}=\{(0,2),(1,1),(2,0)\}
$$

Q.38. Let $\mathrm{h}(\mathrm{n})$ be the impulse response of the LTI causal system described by the difference equation $y(n)=a y(n-1)+x(n)$ and let $h(n) * h_{1}(n)=\delta(n)$. Find $h_{1}(n)$.
Ans:

$$
\begin{array}{lll}
y(n)=a y(n-1)+x(n) & \text { and } & \mathrm{h}(\mathrm{n}) * h_{1}(\mathrm{n})=\delta(\mathrm{n}) \\
\mathrm{Y}(\mathrm{z})=\mathrm{az}^{-1} \mathrm{Y}(\mathrm{z})+\mathrm{X}(\mathrm{z}) & \text { and } & \mathrm{H}(\mathrm{z}) \mathrm{H}_{1}(\mathrm{z})=1 \\
\mathrm{H}(\mathrm{z})=\frac{\mathrm{Y}(\mathrm{z})}{\mathrm{X}(\mathrm{z})}=\frac{1}{1-\mathrm{az}^{-1}} & \text { and } & \mathrm{H}_{1}(\mathrm{z})=\frac{1}{\mathrm{H}(\mathrm{z})} \\
\mathrm{H}_{1}(\mathrm{z})=1-\mathrm{az}^{-1} \quad \text { or } & \mathrm{h}_{1}(\mathrm{n})=\delta(\mathrm{n})-\mathrm{a} \delta(\mathrm{n}-1)
\end{array}
$$

Q.39. Determine the Fourier series expansion of the waveform $f(t)$ shown below in terms of sines and cosines. Sketch the magnitude and phase spectra.
$(10+2+2=14)$
Ans:


Define $g(t)=f(t)+1$. Then the plot of $g(t)$ is as shown, below and,

$\omega=2 \pi / 2 \pi=1$
because $\mathrm{T}=2 \pi$

$$
\begin{aligned}
& \mathrm{g}(\mathrm{t})=\left\{\begin{array}{cc}
0 & -\pi<\mathrm{t}<-\pi / 2 \\
2 & -\pi / 2<\mathrm{t}<\pi / 2 \\
0 & \pi / 2<\mathrm{t}<\pi
\end{array}\right. \\
& \text { Let } g(t)=a_{0}+\sum^{\infty}\left(a_{n} \cos n t+b_{n} \sin n t\right) \\
& \mathrm{n}=1 \\
& \text { Then } \mathrm{a}_{0}=\text { average value of } \mathrm{f}(\mathrm{t})=1 \\
& \mathrm{a}_{\mathrm{n}}=\frac{2}{2 \pi} \int_{-\pi / 2}^{\pi / 2} 2 \cos n t d t=\left.\frac{2}{\pi} \frac{\sin n t}{n}\right|_{-\pi / 2} ^{\pi / 2}=2 / \mathrm{n} \pi \cdot 2 \sin \mathrm{n} \pi / 2 \\
& =4 / \mathrm{n} \pi \cdot \sin \mathrm{n} \pi / 2 \\
& = \begin{cases}0 & \text { if } n=2,4,6 \ldots \ldots \\
4 \ln \pi & \text { if } n=1,5,9 \ldots \ldots \\
-4 / n \pi & \text { if } n=3,7,11 \ldots \ldots\end{cases} \\
& \text { Also, } \mathrm{b}_{\mathrm{n}}=\frac{2}{2 \pi} \int_{-\pi / 2}^{\pi / 2} 2 \sin n t d t=\left.\frac{4}{\pi} \frac{\cos n t}{n}\right|_{\pi / 2} ^{\pi / 2}=4 / \mathrm{n} \pi[\cos \mathrm{n} \pi / 2-\cos \mathrm{n} \pi / 2]=0
\end{aligned}
$$

Thus, we have $f(t)=-1+g(t)$

$$
\begin{aligned}
& =\frac{4 \cos t}{\pi}-\frac{4 \cos 3 t}{3 \pi}+\frac{4 \cos 5 t}{5 \pi}-\ldots \ldots . \\
& =4 / \pi \quad\{\cos t-\cos 3 t / 3+\cos 5 t / 5 \quad \ldots . .\}
\end{aligned}
$$

spectra :

Q.40. Show that if the Fourier Transform (FT) of $x(t)$ is $X(\omega)$, then

$$
\begin{equation*}
\mathrm{FT}\left[\frac{\mathrm{dx}(\mathrm{t})}{\mathrm{dt}}\right]=\mathrm{j} \omega \mathrm{X}(\omega) . \tag{3}
\end{equation*}
$$

Ans:

$$
\begin{aligned}
& \mathrm{x}(\mathrm{t}) \stackrel{\mathrm{FT}}{\longleftrightarrow} \mathrm{X}(\mathrm{j} \omega) \text { or } \mathrm{X}(\omega) \\
& \text { i.e., } \mathrm{x}(\mathrm{t})=\frac{1}{2 \pi} \int_{-\infty}^{+\infty} \mathrm{X}(\mathrm{j} \omega) \mathrm{e}^{\mathrm{j} \omega \mathrm{t}} \mathrm{~d} \omega \\
& \therefore \underset{\mathrm{dt}}{\mathrm{~d}}[\mathrm{x}(\mathrm{t})]=\frac{1}{2 \pi} \int_{-\infty}^{+\infty} \mathrm{X}(\mathrm{j} \omega) \mathrm{j} \omega \mathrm{e}^{\mathrm{j} \omega \mathrm{t}} \mathrm{~d} \omega \\
& \therefore \underset{\mathrm{dt}}{\mathrm{~d}}[\mathrm{x}(\mathrm{t})] \underset{ }{\mathrm{FT}} \mathrm{j} \omega \mathrm{X}(\mathrm{j} \omega)
\end{aligned}
$$

Q.41. Show, by any method, that $\mathrm{FT}\left[\frac{1}{2}\right]=\pi \delta(\omega)$.

Ans:

$$
\begin{aligned}
& \mathrm{x}(\mathrm{t})=\frac{1}{2 \pi} \int_{-\infty} \mathrm{X}(\mathrm{j} \omega) \mathrm{e}^{+\mathrm{j} \omega \mathrm{t}} \mathrm{~d} \omega \\
& \mathrm{x}(\mathrm{t})=\frac{1}{2 \pi} \int_{-\infty}^{+\infty} \pi \delta(\omega) \mathrm{e}^{\mathrm{j} \omega \mathrm{t}} \mathrm{~d} \omega=\frac{1}{2} \quad \because \mathrm{X}(\mathrm{j} \omega)=\pi \delta(\omega) \\
& \therefore \frac{1}{2} \stackrel{\mathrm{FT}}{\longleftrightarrow} \pi \delta(\omega)
\end{aligned}
$$

Q. 42 Find the unit impulse response, $h(t)$, of the system characterized by the relationship :

$$
\begin{equation*}
\mathrm{y}(\mathrm{t})=\int_{-\infty}^{\mathrm{t}} \mathrm{x}(\tau) \mathrm{d} \tau \tag{3}
\end{equation*}
$$

Ans:

$$
\mathrm{y}(\mathrm{t})=\int_{-\infty}^{\mathrm{t}} \delta(\tau) \mathrm{d} \tau=\left\{\begin{array}{l}
1, \mathrm{t} \geq 0=\mathrm{u}(\mathrm{t}) \\
0, \text { otherwise }
\end{array}\right.
$$

Q.43. Using the results of parts (a) and (b), or otherwise, determine the frequency response of the system of part (c).

## Ans:



As shown in the figure, $u(t)=1 / 2+x(t)$
where $\mathrm{x}(\mathrm{t})=\left\{\begin{aligned} 0.5, & \mathrm{t}>0 \\ -0.5, & \mathrm{t}<0\end{aligned}\right.$
$\therefore \mathrm{dx} / \mathrm{dt}=\delta(\mathrm{t}) \mathrm{By}(\mathrm{a}) \mathrm{FT}[\delta(\mathrm{t})]=\mathrm{j} \omega \mathrm{X}(\omega)$
$\therefore \mathrm{X}(\omega)=1 / \mathrm{j} \omega$. Also FT[1/2] $=\pi \delta(\omega)$
Therefore FT $[u(t)]=H(j \omega)=\pi \sqrt{ }(\omega)+1 / j \omega$.
Q.44. Let $X\left(\mathrm{e}^{\mathrm{j} \omega}\right)$ denote the Fourier Transform of the signal $\mathrm{x}(\mathrm{n})$ shown below.$(\mathbf{2}+\mathbf{2}+\mathbf{3 + 5 + 2 = 1 4 )}$

Ans:


Without explicitly finding out $\mathrm{X}\left(\mathrm{e}^{\mathrm{j} \omega}\right)$, find the following :-
(i) $\mathrm{X}(1)$
(ii) $\int_{-\pi}^{\pi} \mathrm{X}\left(\mathrm{e}^{\mathrm{j} \omega}\right) \mathrm{d} \omega$
(iii) $\mathrm{X}(-1)$
(iv) the sequence $\mathrm{y}(\mathrm{n})$ whose Fourier

Transform is the real part of $X\left(\mathrm{e}^{\mathrm{j} \omega}\right)$.
(v) $\int_{-\pi}^{\pi}\left|X\left(e^{j \omega}\right)\right|^{2} d \omega$.

Ans:

$$
X\left(e^{j \omega}\right)=\sum_{n=-\infty}^{\infty} x(n) e^{-j \omega n}
$$

$$
+\infty
$$

(i) $\mathrm{X}(1)=\mathrm{X}\left(\mathrm{e}^{\mathrm{j} 0}\right)=\sum_{-\infty} \mathrm{x}(\mathrm{n})=-1+1+2+1+1+2+1-1=6$
(ii) $x(n)=\frac{1}{2 \pi} \int_{-\pi}^{+\pi} X\left(e^{j \omega}\right) e^{j \omega n} d \omega ; \int_{-\pi}^{\pi} X\left(e^{j \omega}\right) d \omega=2 \pi x(0)=4 \pi$
(iii) $\mathrm{X}(-1)=\mathrm{X}\left(\mathrm{e}^{\mathrm{j} \pi}\right)=\sum_{\mathrm{n}=-\infty}^{+\infty} \mathrm{x}(\mathrm{n})(-1)^{\mathrm{n}}=1+0-1+2-1+0-1+2-1+0+1=2$
(iv) Real part $\mathrm{X}\left(\mathrm{e}^{\mathrm{j} \omega}\right) \longleftrightarrow \mathrm{X}_{\mathrm{e}}(\mathrm{n})=\frac{\mathrm{x}(\mathrm{n})+\mathrm{x}(-\mathrm{n})}{2}$

$$
\begin{aligned}
& y(n)=x_{e}(n)=0, \quad n<-7, n>7 \\
& y(7)=\frac{1}{2} x(7)=-\frac{1}{2}=y(-7) \\
& y(6)=\frac{1}{2} x(6)=0=y(-6) \\
& y(5)=\frac{1}{2} x(5)=\frac{1}{2}=y(-5) \\
& y(4)=\frac{1}{2} x(4)=2=y(-4) \\
& y(3)=\frac{1}{2}[x(3)+x(-3)]=0=y(-3) \\
& y(2)=\frac{1}{2}[x(2)+x(-2)]=0=y(-2) \\
& y(1)=\frac{1}{2}[y(1)+y(-1)]=1=y(-1) \\
& y(0)=\frac{1}{2}[y(0)+y(0)]=2
\end{aligned}
$$

(v) Parseval's theorem:

$$
\int_{-\pi}^{\pi}\left|X\left(e^{j \omega}\right)\right|^{2} d \omega=2 \pi \sum_{n=-\infty}^{\infty}|x(n)|^{2}=2 \pi(1+1+4+1+1+4+1+1)=28 \pi
$$

Q. 45 If the z-transform of $x(n)$ is $X(z)$ with ROC denoted by $R_{x}$, find the

$$
\begin{equation*}
\text { z-transform of } y(n)=\sum_{k=-\infty}^{n} x(k) \text { and its ROC. } \tag{4}
\end{equation*}
$$

Ans:

$$
\begin{aligned}
& \mathrm{x}(\mathrm{n}) \underset{\mathrm{n}}{\stackrel{\mathrm{Z}}{\longleftrightarrow}} \mathrm{X}(\mathrm{z}),{ }_{0}^{\operatorname{RoCR} \mathrm{R}_{\mathrm{x}}} \\
& y(n)=\sum_{k=-\infty}^{n} x(k)=\quad \sum_{k=\infty}^{0} x(n-k)=\sum_{k=0}^{\infty} x(n-k) \\
& Y(z)=X(z) \underbrace{\sum_{k=0}^{\infty} z^{-k}}=\frac{X(z)}{1-z^{-1}}, \text { RoC at least } R_{x} \cap(|z|>1)
\end{aligned}
$$

Geometric series
Q. 46 (i) $x(n)$ is a real right-sided sequence having a $z$-transform $X(z) . X(z)$ has two poles, one of which is at a $e^{j \phi}$ and two zeros, one of which is at $r e^{-j \theta}$. It is also known that $\sum \mathrm{x}(\mathrm{n})=1$. Determine $\mathrm{X}(\mathrm{z})$ as a ratio of polynomials in $\mathrm{z}^{-1}$.
(ii) If $\mathrm{a}=1 / 2, \mathrm{r}=2, \theta=\phi=\pi / 4$ in part (b) (i), determine the magnitude of $\mathrm{X}(\mathrm{z})$ on the unit circle.

## Ans:

(i) $\mathrm{x}(\mathrm{n})$ : real, right-sided sequence $\stackrel{\mathrm{Z}}{\longleftrightarrow} \mathrm{X}(\mathrm{z})$

$$
\begin{aligned}
X(z) & =K \frac{\left(z-r e^{-j \theta}\right)\left(z-r e^{j \theta}\right)}{\left(z-a e^{j \Phi}\right)\left(z-a e^{-j \Phi}\right)} \quad ; \sum x(n)=X(1)=1 \\
& =K \frac{z^{2}-z r\left(e^{j \theta}+e^{-j \theta}\right)+r^{2}}{z^{2}-z a\left(e^{j \Phi}+e^{j \Phi}\right)+a^{2}} \\
& =K \frac{1-2 r \cos \theta z^{-1}+r^{2} z^{-2}}{1-2 a \cos \Phi z^{-1}+a^{2} z^{-2}}=K \cdot \frac{N\left(z^{-1}\right)}{D\left(z^{-1}\right)}
\end{aligned}
$$

where K. $\frac{1-2 \mathrm{r} \cos \theta+\mathrm{r}^{2}}{1-2 \mathrm{a} \cos \Phi+\mathrm{a}^{2}}=\mathrm{X}(1)=1$

$$
\begin{aligned}
& \text { i.e., } K=\frac{1-2 \mathrm{a} \cos \Phi+\mathrm{a}^{2}}{1-2 \mathrm{r} \cos \theta+\mathrm{r}^{2}} \\
& \text { (ii) } \mathrm{a}=1 / 2, \mathrm{r}=2, \theta=\Phi=\pi / 4 ; \mathrm{K}=\frac{1-2(1 / 2) \cdot(1 / \sqrt{ } 2)+1 / 4}{1-2(2)(1 / \sqrt{ } 2)+4}=0.25 \\
& \mathrm{X}(\mathrm{z})=(0.25) \cdot \frac{1-2(2)(1 / \sqrt{ } 2) \mathrm{z}^{-1}+4 \mathrm{z}^{-2}}{1-2(1 / 2) \cdot(1 / \sqrt{ } 2) \mathrm{z}^{-1}+1 / 4 \mathrm{z}^{-2}} \\
& =(0.25) \frac{1-2 \sqrt{ } 2 \mathrm{z}^{-1}+4 \mathrm{z}^{-2}}{1-(1 / \sqrt{2}) \mathrm{z}^{-1}+1 / 4 \mathrm{z}^{-2}} \Rightarrow \mathrm{X}\left(\mathrm{e}^{\mathrm{j} \omega}\right)=\quad(0.25) \frac{1-2 \sqrt{ } 2 \mathrm{e}^{-\mathrm{j} \omega}+4 \mathrm{e}^{-2 \mathrm{j} \omega}}{1-(1 / \sqrt{ } 2) \mathrm{e}^{-\mathrm{j} \omega}+1 / 4 \mathrm{e}^{-2 j \omega}} \\
& =\frac{-2 \sqrt{ } 2+\mathrm{e}^{\mathrm{j} \omega}+4 \mathrm{e}^{-\mathrm{j} \omega}}{-2 \sqrt{ } 2+4 \mathrm{e}^{\mathrm{j} \omega}+\mathrm{e}^{-\mathrm{j} \omega}} \\
& \therefore\left|\mathrm{X}\left(\mathrm{e}^{\mathrm{j} \omega}\right)\right|=1
\end{aligned}
$$

Q. 47 Determine, by any method, the output $\mathrm{y}(\mathrm{t})$ of an LTI system whose impulse response $h(t)$ is of the form shown in fig(a). to the periodic excitation $x(t)$ as shown in fig(b).
Ans:


Fig(a)


Fig(b)
$\mathrm{h}(\mathrm{t})=\mathrm{u}(\mathrm{t})-\mathrm{u}(\mathrm{t}-1) \quad \Rightarrow \mathrm{H}(\mathrm{s})=\frac{1-\mathrm{e}^{-\mathrm{s}}}{s}$
First period of $\mathrm{x}(\mathrm{t}), \mathrm{x}_{\mathrm{T}}(\mathrm{t})=2 \mathrm{t}[\mathrm{u}(\mathrm{t})-\mathrm{u}(\mathrm{t}-1 / 2)]$
$=2[\mathrm{tu}(\mathrm{t})-(\mathrm{t}-1 / 2) \mathrm{u}(\mathrm{t}-1 / 2)-1 / 2 \mathrm{u}(\mathrm{t}-1 / 2)]$
$\therefore \mathrm{X}_{\mathrm{T}}(\mathrm{s})=2\left[1 / \mathrm{s}^{2}-\mathrm{e}^{-\mathrm{s} / 2} / \mathrm{s}^{2}-1 / 2 \mathrm{e}^{-\mathrm{s} / 2} / \mathrm{s}\right]$
$\mathrm{X}(\mathrm{s})=\mathrm{X}_{\mathrm{T}}(\mathrm{s}) / 1-\mathrm{e}^{-\mathrm{s} / 2}$
$\mathrm{Y}(\mathrm{s})=\frac{1 e^{e-s}}{s} \cdot \frac{1}{1-e^{-s / 2}} 2\left(\frac{1-e^{-s / 2}-0.5 s e^{-s / 2}}{s^{2}}\right)$
$=\frac{2}{\mathrm{~s}^{3}}\left(1+\mathrm{e}^{-\mathrm{s} / 2}\right)\left[1-\mathrm{e}^{-\mathrm{s} / 2}-0.5 \mathrm{~s} \mathrm{e}^{-\mathrm{s} / 2}\right]$
$=\frac{2}{s^{3}}\left(1-e^{-s}-0.5 s\left(e^{-s / 2}+e^{-s}\right)\right)$
$=2 \frac{1-e^{-s}}{s^{3}}-\frac{e^{-s / 2}+e^{-s}}{s^{2}}$
Therefore $\mathrm{y}(\mathrm{t})=\mathrm{t}^{2} \mathrm{u}(\mathrm{t})-(\mathrm{t}-1)^{2} \mathrm{u}(\mathrm{t}-1)-\left(\mathrm{t}-\frac{1}{2}\right) \mathrm{u}\left(\mathrm{t}+\frac{1}{2}\right)-(\mathrm{t}-1) \mathrm{u}(\mathrm{t}-1)$

This gives $\mathrm{y}(\mathrm{t})=\left\{\begin{array}{lr}\mathrm{t} 2 & 0<\mathrm{t}<1 / 2 \\ \mathrm{t}^{2}-\mathrm{t}+1 / 2 & 1 / 2<\mathrm{t}<1 \\ 1 / 2 & \mathrm{t}>1\end{array}\right.$

Q. 48 Obtain the time function $f(t)$ whose Laplace Transform is $F(s)=\frac{s^{2}+3 s+1}{(s+1)^{3}(s+2)^{2}}$.

Ans:

$$
\begin{aligned}
& \mathrm{F}(\mathrm{~s})=\frac{\mathrm{s}^{2}+3 \mathrm{~s}+1}{(\mathrm{~s}+1)^{3}(\mathrm{~s}+2)^{2}}=\frac{\mathrm{A}}{(\mathrm{~s}+1)}+\frac{\mathrm{B}}{(\mathrm{~s}+1)^{2}}+\frac{\mathrm{C}}{(\mathrm{~s}+1)^{3}}+\frac{\mathrm{D}}{(\mathrm{~s}+2)}+\frac{\mathrm{E}}{(\mathrm{~s}+2)^{2}} \\
& \mathrm{~A}(\mathrm{~s}+2)^{2}(\mathrm{~s}+1)^{2}+\mathrm{B}(\mathrm{~s}+2)^{2}(\mathrm{~s}+1)+\mathrm{C}(\mathrm{~s}+2)^{2}+\mathrm{D}(\mathrm{~s}+1)^{3}(\mathrm{~s}+2)+\mathrm{E}(\mathrm{~s}+1)^{3}=\mathrm{s}^{2}+3 \mathrm{~s}+1 \\
& C=\left.\frac{\mathrm{s}^{2}+3 \mathrm{~s}+1}{(\mathrm{~s}+2)^{2}}\right|_{\mathrm{s}=-1}=\frac{1-3+1}{1}=-1 \\
& C=-1 \\
& E=\left.\frac{s^{2}+3 s+1}{(s+1)^{3}}\right|_{s=-2}=\frac{4-6+1}{-1}=1 \\
& \mathrm{E}=1 \\
& \mathrm{~A}\left(\mathrm{~s}^{2}+3 \mathrm{~s}+2\right)^{2}+\mathrm{B}\left(\mathrm{~s}^{2}+4 \mathrm{~s}+4\right)(\mathrm{s}+1)+\mathrm{C}\left(\mathrm{~s}^{2}+4 \mathrm{~s}+4\right)+\mathrm{D}\left(\mathrm{~s}^{3}+3 \mathrm{~s}^{2}+3 \mathrm{~s}+1\right)(\mathrm{s}+2)+\mathrm{E}\left(\mathrm{~s}^{3}+3 \mathrm{~s}^{2}+3 \mathrm{~s}+1\right) \\
& =\mathrm{s}^{2}+3 \mathrm{~s}+1 \\
& \mathrm{~A}\left(\mathrm{~s}^{4}+6 \mathrm{~s}^{3}+13 \mathrm{~s}^{2}+12 \mathrm{~s}+4\right)+\mathrm{B}\left(\mathrm{~s}^{3}+5 \mathrm{~s}^{2}+8 \mathrm{~s}+4\right)+\mathrm{C}\left(\mathrm{~s}^{2}+4 \mathrm{~s}+4\right)+\mathrm{D}\left(\mathrm{~s}^{4}+5 \mathrm{~s}^{3}+9 \mathrm{~s}^{2}+7 \mathrm{~s}+2\right)+ \\
& E\left(s^{3}+3 s^{2}+3 s+1\right)=s^{2}+3 s+1 \\
& \mathrm{~s}^{4}: \quad \mathrm{A}+\mathrm{D}=0 \\
& \mathrm{~s}^{3}: 6 \mathrm{~A}+\mathrm{B}+5 \mathrm{D}+\mathrm{E}=0 \quad ; \quad \mathrm{A}+\mathrm{B}+1=0 \quad \text { as } 5(\mathrm{~A}+\mathrm{D})=0, \mathrm{E}=1 \\
& \mathrm{~s}^{2}: 13 \mathrm{~A}+5 \mathrm{~B}+\mathrm{C}+9 \mathrm{D}+3 \mathrm{E}=1 \quad ; 4 \mathrm{~A}+5 \mathrm{~B}+1=0 \quad \text { as } 9(\mathrm{~A}+\mathrm{D})=0, \mathrm{C}=-1, \mathrm{E}=1 \\
& \mathrm{~s}^{1}: 12 \mathrm{~A}+8 \mathrm{~B}+4 \mathrm{C}+7 \mathrm{D}+3 \mathrm{E}=3 ; 5 \mathrm{~A}+8 \mathrm{~B}-4=0 \quad \text { as } 7(\mathrm{~A}+\mathrm{D})=0, \mathrm{C}=-1, \mathrm{E}=1 \\
& \mathrm{~s}^{0}: 4 \mathrm{~A}+4 \mathrm{~B}+4 \mathrm{C}+2 \mathrm{D}+\mathrm{E}=1
\end{aligned}
$$

$\mathrm{A}+\mathrm{B}=-1 ; 4(\mathrm{~A}+\mathrm{B})+\mathrm{B}+1=0$ or $-4+\mathrm{B}+1=0$ or $\square$

$$
\mathrm{A}=-4
$$

$A=-1-3=-4$
$\mathrm{A}+\mathrm{D}=0$ or $\mathrm{D}=-\mathrm{A}=4$
$\mathrm{F}(\mathrm{s})=\frac{-4}{(\mathrm{~s}+1)}+\frac{3}{(\mathrm{~s}+1)^{2}}+\frac{-1}{(\mathrm{~s}+1)^{3}}+\frac{4}{(\mathrm{~s}+2)}+\frac{1}{(\mathrm{~s}+2)^{2}}$
$\therefore f(t)=L^{-1}[F(s)]=-4 e^{-t}+3 t e^{-t}-t^{2} e^{-t}+4 e^{-2 t}+t e^{-2 t}=\left[e^{-t}\left(-4+3 t-t^{2}\right)+e^{-2 t}(4+t)\right] u(t)$
$\therefore f(t)=\left[e^{-t}\left(-4+3 t-t^{2}\right)+e^{-2 t}(4+t)\right] u(t)$
Q. 49 Define the terms variance, co-variance and correlation coefficient as applied to random variables.

## Ans:

Variance of a random variable X is defined as the second central moment
$\mathrm{E}\left[\left(\mathrm{X}-\mu_{\mathrm{x}}\right)\right]^{\mathrm{n}}, \mathrm{n}=2$, where central moment is the moment of the difference between a random variable X and its mean $\mu_{\mathrm{x}}$ i.e.,

$$
\sigma_{x^{2}}=\operatorname{var}[\mathrm{X}] \int_{-\infty}^{+\infty}\left(\mathrm{x}-\mu_{\mathrm{x}}\right)^{2} \mathrm{f}_{\mathrm{x}}(\mathrm{x}) \mathrm{dx}
$$

Co-variance of random variables X and Y is defined as the joint moment:

$$
\sigma_{\mathrm{XY}}=\operatorname{cov}[\mathrm{XY}]=\mathrm{E}[\{\mathrm{X}-\mathrm{E}[\mathrm{X}]\}\{\mathrm{Y}-\mathrm{E}[\mathrm{Y}]\}]=\mathrm{E}[\mathrm{XY}]-\mu_{\mathrm{X}} \mu_{\mathrm{Y}}
$$

where $\mu_{\mathrm{x}}=\mathrm{E}[\mathrm{X}]$ and $\mu_{\mathrm{Y}}=\mathrm{E}[\mathrm{Y}]$.
Correlation coefficient $\rho_{X Y}$ of $X$ and $Y$ is defined as the co-variance of $X$ and $Y$ normalized
w.r.t $\sigma_{X} \sigma_{Y}$ :

$$
\rho_{X Y}=\frac{\operatorname{cov}[X Y]}{\sigma_{X} \sigma_{Y}}=\frac{\sigma_{X Y}}{\sigma_{X} \sigma_{Y}}
$$

